

ION NTM 2007 Proceedings

Table of Contents

Plenary Session

Remote Sensing of Earth

K. Schuckman, *URS Corporation* ----- 1

Monitoring Weather, Climate and Space Weather with GPS: The COSMIC/FORMOSAT-3 Mission

B. Kuo, *University Corporation for Atmospheric Research (COSMIC)*-----20

Improving GNSS for Future Natural Disaster Reduction: *Earthquakes & Tsunamis*

K.W. Hudnut, *U.S. Geological Survey*-----56

Session A1: Advanced Topics in Location-Based Services

From Divergence to Convergence, GNSS Assistance in Network Carrier Independent Format

K. Alanen, J. Syrjärinne, *Nokia Technology Platforms, Finland*-----85

GPS PRN Code Signal Processing and Receiver Design for Simultaneous All-in-View Coherent Signal Acquisition and Navigation Solution Determination

R. DiEsposti, *General Dynamics Advanced Information Systems* -----91

Geoencryption Using Loran

D. Qiu, S. Lo, P. Enge, D. Boneh, *Stanford University*; B. Peterson,
Peterson Integrated Geopositioning ----- 104

Automatic Sorting and Storage Based on Location Information for Massive Human-Centric Data Collection

D. Bhupathiraju, P.K. Sagiraju, D. Akopian, *University of Texas at San Antonio*----- 116

GPS Tracking Location-Based Service Using the Wristwatch GeoZigBee Sensors

A. Brown, J. Griesbach, B. Bockius, *NAVSYS Corporation*; T. Boulton, *University of Colorado at Colorado Springs* ----- 123

Personal Navigation on a Cellular Telephone

P. Duffett-Smith, S. Hern, P. Hansen, *Cambridge Silicon Radio, U.K.*; A.R. Pratt, *Orbstar Consultants, U.K.* ----- 133

Session A2: Algorithms and Methods 1

Adaptive Carrier Smoothing Using Code and Carrier Divergence

E. Kim, T. Walter, J.D. Powell, *Stanford University* ----- 141

Performance Study of Reduced Search FFT-Based Acquisition

P.K. Sagiraju, D. Akopian, G.V.S. Raju, *University of Texas at San Antonio*----- 153

Static and Dynamic Performance of a Novel GPS Attitude Determination Algorithm (GADA)

N.P. Oliveira Leite, *Grupo Especial de Ensaios em Vôo (GEEV), Brazil*; F. Walter, *Instituto Tecnológico de Aeronáutica, Brazil* ----- 161

Integer Ambiguity Resolution for GPS Attitude Determination From Double Difference Phase Measurements

C. Cardani, A. Rolando, *Politecnico di Milano, Italy*; C. Di Marino, P. Vercesi, *GPSAeroborne Srl, Italy*----- 172

Yaw Angle Estimation of VTOL-UAVs with the Extended LAMBDA Method and Low Cost Receivers

R. Mönikes, O. Meister, J. Wendel, G.F. Trommer, *University of Karlsruhe, Germany*----- 179

Proving the Integrity of the Weighted Sum Squared Error (WSSE) Loran Cycle Confidence Algorithm

S.C. Lo, *Stanford University*; B.B. Peterson, *Peterson Integrated Geopositioning*; P.K. Enge, *Stanford University* ----- 187

Yet Another FDE for Multiple Outliers

E. Zemskov, J. Nurmi, *Tampere University of Technology, Finland* ----- 201

Session A3: GNSS Interoperability and Compatibility

A Glimpse into the Future: A Look at GNSS in the Year 2017

J.W. Lavrakas, *Advanced Research Corporation* ----- 210

Exploring GNSS RTK Performance Benefits with GPS and Virtual Galileo Measurements

Y. Feng, *Queensland University of Technology, Australia*; J. Wang, *The University of New South Wales, Australia*----- 218

1-Bit Processing of Composite BOC (CBOC) Signals and Extension to Time-Multiplexed BOC (TMBOC) Signals

O. Julien, C. Macabiau, *ENAC, France*; J-L. Issler, L. Ries, *CNES, France* ----- 227

Hardware and Algorithm Implications of Adding Galileo Capability to an SPS GPS Receiver

P.G. Mattos, *ST Microelectronics, U.K.* ----- 240

A New Waveform Family for Secondary Peaks Rejection in Code Tracking Discriminators for Galileo BOC(n,n) Modulated Signals

G. Avellone, M. Frazzetto, E. Messina, *STMicroelectronics, Italy*----- 246

Visibility and Geometry of Combined Constellations GPS and Galileo
J. Januszewski, *Gdynia Maritime University, Poland*----- 252

GIS Simulation for Estimating Satellite Visibility and Positioning Accuracy in an Integrated GNSS Environment
Y-W. Lee, *The University of Tokyo, Japan*; Y-C. Suh, *Pukyong National University, Korea*;
R. Shibasaki, *The University of Tokyo, Japan*----- 263

Session A4: Augmentation Systems: GBAS and SBAS

Comparison of Alternative Methods for Deriving Ground Monitor Requirements for CAT IIIB LAAS
C.A. Shively, *The MITRE Corporation/CAASD* ----- 267

Multi-constellation Augmentation Based on EGNOS and Galileo Simulation
R. Chen, *Finnish Geodetic institute, Finland*; P. Cheng, *Chinese Academy of Surveying and Mapping, China*; T. Moore, C. Hill, *IESSG, University of Nottingham, U.K.*; A. Hyttinen, X. Li, Y. Chen, T. Johler, *Finnish Geodetic Institute, Finland*; Y. Cai, *Chinese Academy of Surveying and Mapping, China* ----- 285

WAAS Performance Improvement with a New Undersampled Ionospheric Gradient Threat Model Metric
N. Pandya, M. Gran, E. Paredes, *Raytheon Company* ----- 291

Understanding PHMI for Safety of Life Applications in GNSS
J. Blanch, T. Walter, P. Enge, *Stanford University* ----- 305

Session B1: Integrated Navigation Systems 1

A Simplified Method for Deep Coupling of GPS and Inertial Data
R.N. Crane, *L-3 Communications, Interstate Electronics Corporation* ----- 311

An Intelligent Scheme for Rapid INS Alignment Procedure Using Artificial Neural Networks
Y-W. Huang, Y-S. Huang, K-W. Chiang, *National Cheng Kung University, Taiwan*----- 320

Testing an Algorithm for Processing Delayed and Non-delayed Measurements
R. Ingvalson, *Honeywell International Inc.*; H. Rotstein, *RAFAEL, The Armament Development Authority, Israel*----- 327

Design and Testing of a High Performance Relative Inertial Navigation System
B. Mohr, R. Ingvalson, L.C. Vallot, W.A. Soehren, *Honeywell Aerospace Advanced Technology*; M.B. Ignagni, *NavSolutions*; J. Campbell, M.M. Miller, M. Berarducci, P. Howe, *Air Force Research Laboratory*----- 334

Thermal Calibration of Low Cost MEMS Sensors for Integrated Positioning, Navigation Systems
P. Aggarwal, Z. Syed, X. Niu, N. El-Sheimy, *The University of Calgary, Canada*----- 343

Design of Miniature RF Band-pass Filters for a Hybrid GPS/Galileo Receiver Front-End Insert
Y. Adane, A. Constantinescu, J. Belzile, A. Kouki, *Ecole de Technologie Supérieure, Canada* ----- 350

ASF Correction Within an Integrated Navigation System of Loran-C / RDSS	
H. Chen, X. Chen, <i>Chinese Academy of Sciences, China</i> -----	357

Session B2: Interference and Spectrum Management

Assessment of Interference to the Galileo E5b Signal in the United States	
M. Tran, C. Hegarty, Y-S. Hoh, D. O'Laughlin, <i>The MITRE Corporation</i> -----	361

GPS PRN Code Assignment Process	
S.H. Raghavan, <i>The Aerospace Corporation</i> ; L.M. Vaughn, <i>U.S. Air Force GPS Wing</i> ; S.K. Yi, <i>ARINC</i> -----	372

On Coexistence of In-band UWB-OFDM and GPS Signals	
D. Garmatyuk, Y.J. Morton, <i>Miami University</i> -----	378

On Quantifying the Potential Interference of Ultra Wideband Signals to the 960-1610 MHz Radio Navigation Frequency Band	
N.A. Morgan, V.S. Lin, R. Yowell, <i>The Aerospace Corporation</i> ; L. Vaughn, <i>U.S. Air Force, GPS Wing</i> -----	386

GPS Interference Sources Angle of Arrival Estimation Using an Adaptive Periodogram Technique	
M. Brenneman, Y.T. Morton, Q. Zhou, G. Distler, <i>Miami University</i> -----	398

Session B3: QZSS: Quasi-Zenith Satellite System (QZSS)

QZSS System Design and its Performance	
M. Kishimoto, H. Hase, A. Matsumoto, T. Tsuruta, S. Kogure, N. Inaba, M. Sawabe, T. Kawanishi, S. Yoshitomi, K. Terada, <i>Japan Aerospace Exploration Agency, Japan</i> -----	405

Augmentation Performance of QZSS L1-SAIF Signal	
T. Sakai, S. Fukushima, N. Takeichi, K. Ito, <i>Electronic Navigation Research Institute, Japan</i> -----	411

The On-board and Ground Time Management System of QZSS	
Y. Takahashi, J. Amagai, S. Hama, M. Fujieda, K. Kimura, <i>National Institute of Information and Communications Technology, Japan</i> ; T. Takahashi, T. Nakahara, S. Horiuchi, <i>NEC Toshiba Space Systems, Ltd., Japan</i> -----	422

Remote Synchronization System of Quasi-Zenith Satellites Using Multiple Positioning Signals for Feedback Control	
T. Iwata, Y. Kawasaki, M. Imae, T. Suzuyama, T. Matsuzawa, <i>National Institute of Advanced Industrial Science and Technology, Japan</i> ; S. Fukushima, Y. Hashibe, <i>Space Engineering Development Co. Ltd., Japan</i> ; N. Takasaki, K. Kokubu, A. Iwasaki, <i>University of Tokyo, Japan</i> ; F. Tappero, A. Dempster, <i>University of New South Wales, Australia</i> ; Y. Takahashi, <i>National Institute of Information and Communications Technology, Japan</i> -----	427

Research into the Application of Integrated RTK-GPS/INS Systems for IT Construction	
K. Fujimoto, H. Matsushita, <i>National Institute for Land and Infrastructure, Japan</i> ; Y. Shimogaki, <i>Hitachi, Ltd., Japan</i> ; M. Tanikawara, <i>Hitachi Industrial Equipment Systems Co.,Ltd., Japan</i> -----	436

Development of a BOC/CA Pseudo QZS and Multipath Analysis Using an Airborne Platform
T. Tsujii, H. Tomita, Y. Okuno, S. Kogure, M. Kishimoto, *Japan Aerospace Exploration Agency, Japan*; K. Okano, D. Manandhar, I. Petrovski, M. Asako, *Institute of Advanced Satellite Positioning Technology, GNSS Technologies Inc., Japan* -----446

Development and Performance Evaluation of Spaceborne Hydrogen Maser Atomic Clock in NICT
H. Ito, T. Morikawa, S. Hama, *National Institute of Information and Communications Technology, Japan*; M. Takizawa, Y. Numata, S. Mattori, *Anritsu Corporation, Japan* -----452

Future Expansion From QZSS to Regional Satellite Navigation System
S. Kogure, M. Kishimoto, M. Sawabe, *Japan Aerospace Exploration Agency, Japan* -----455

Session B4: Applications in Surveying, Geodesy, Science, and Timing

New Application of Reflected GPS Signals L1/L2 Observation Techniques with an Integrated GPS Receiver for Ground Object Detection and Digital Terrain Elevation Mapping
L-C. Shen, C-L. Tseng, J-C. Juang, *National Cheng Kung University, Taiwan*;
C-C. Chang, *Yuda University, Taiwan*-----461

Impact of Ocean Tide Models on GPS Observations
L. Santos, V.B. Mendes, *University of Lisboa, Portugal* -----473

Coordinate-space and Observation-space Filtering Methods for Sidereally Repeating Errors in GPS: Performance and Filter Lifetime
A.E. Ragheb, P.J. Clarke, S.J. Edwards, *University of Newcastle, U.K.*-----480

Augmenting GPS with Pseudolites for Deformation Monitoring in Harsh Environments
J. Bond, A. Chrzanowski, D. Kim, *University of New Brunswick, Canada*-----486

Geodetic Grade Airborne LiDAR Mapping
N. Csanyi, K. Edwards, D. Grejner-Brzezinska, C. Toth, *The Ohio State University*-----493

Test Results From a Novel Passive Bistatic GPS Radar Using a Phased Sensor Array
A. Brown, B. Mathews, *NAVSYS Corporation*-----504

Session C1: Integrated Navigation Systems 2

Improving the Positioning Accuracy of a Low Cost MEMS/GPS Integrated System Using GPS Heading Sensors
Y-W. Huang, C-Y. Li, H-W Wu, H-W. Chang, H-W. Hu, K-W. Chiang, *National Cheng-Kung University, Taiwan* -----510

Adaptive Knowledge-based System for Personal Navigation in GPS-denied Environments
D.A. Grejner-Brzezinska, C. Toth, S. Moafipoor, *The Ohio State University*; J. Kwon, *University of Seoul, Korea* -----517

Realization of a Deeply Coupled GPS/INS Navigation System Based on INS-VDLL Integration
S. Kiesel, M.M. Held, G.F. Trommer, *University of Karlsruhe, Germany* -----522

IMU Signal Software Simulator

Y. Yang, N. El-Sheimy, C. Goodall, X. Niu, *University of Calgary, Canada* -----532

Session C2: GPS Modernization and GPS III

The Spreading and Overlay Codes for the L1C Signal

J.J. Rushanan, *The MITRE Corporation* -----539

Proposed Operations Concepts and Flexible UE Architectures for Modernized User Equipment SIS Utilization for Transition From Test Mode to IOC through FOC

R. DiEsposti, *General Dynamics Advanced Information Systems*; K. Hsu,
The Boeing Company-----548

A Theoretical Survey of the Spreading Modulation of the New GPS Signals (L1C, L2C, and L5)

I.F. Proгри, *Giffet Inc.*; M.C. Bromberg, *Elected Engineering*; W.R. Michalson, *Worcester
Polytechnic Institute*; J. Wang, *University of New South Wales, Australia* -----561

Session C3: Algorithms and Methods 2

Analysis of Discriminator Based Vector Tracking Algorithms

M. Lashley, D.M. Bevely, *Auburn University*-----570

Theoretical Data on Support of a Unified Indoor Geolocation Channel Model

I.F. Proгри, *Giffet Inc.*; W.R. Michalson, *Worcester Polytechnic Institute*; J. Wang,
University of New South Wales, Australia; M.C. Bromberg, *Elected Engineering*-----577

GNSS Receiver Tracking Loss and Cycle Slip Detection Using Frequency Lock Loop Phase Acceleration and Jerk Estimation

T. Kim, *NavCom Technology, Inc.*; H. So, S.J. Choi, C. Kee; *Seoul National University,
Korea*-----585

Multi-C/A Code Acquisition Method

Y-C. Lin, S-S. Jan, *National Cheng Kung University, Taiwan* -----594

Session C4: Space Navigation Applications

Feasibility Analysis on the Application of GPS Relative Positioning in LEO Constellations

S. Wang, T. Moore, C. Hill, C. Noakes, A. Dodson, *University of Nottingham, U.K.*-----603

Integrated Spacecraft Entry Navigation on the Electra Programmable Radio

M.C. Heyne, R.H. Bishop, *The University of Texas at Austin* -----615

Software Simulation Tests and Results for Nano-Satellite Formation Flying

Q. Marji, R. Tsoi, M.E. Cannon, *The University of Calgary, Canada*; R.E. Zee,
University of Toronto, Canada -----628

Comparison of Acquisition Techniques for GNSS Signal Processing in Geostationary Orbit

B. Chibout, C. Macabiau, A-C. Escher, *Ecole Nationale de l'Aviation Civile/Tesa, France*;
L. Ries, J-L. Issler, *CNES, France*; S. Corrazza, *Alcatel Alenia Space*; M. Bousquet, *Supaero* -----637

Session C5: Receiver and Antenna Technologies

Prediction of Antenna and Antenna Electronics Induced Biases in GNSS Receivers

I. Gupta, C. Church, A. O'Brien, C. Slick, *The Ohio State University*----- 650

Tight Integration of a GPS Adaptive Array with a Software-Defined Receiver

S.K. Kalyanaraman, M.S. Braasch, *Ohio University*----- 657

A Blind Beamforming Technique for Simultaneous Interference Suppression and Signal Maximization in Multiple Antenna GPS Systems

A.L. Anderson, J.R. Zeidler, *University of California, San Diego*; M. Nicholson, B. Hoffman, *Space and Naval Warfare Systems Center, San Diego* ----- 669

A Reduced Size CRPA (R-CRPA) for GNSS Receivers

I. Gupta, J. Volakis, C-C. Chen, *The Ohio State University*----- 675

A Novel Flexible Correlator Architecture for GNSS Receivers

V. Eerola, S. Pietilä, H. Valio, *Nokia Corporation, Finland* ----- 681

RTCA Airborne GPS Antenna Testing and Analysis for a New Antenna Minimum Operational Performance Standards (MOPS)

A.J. Van Dierendonck, *AJ Systems*; R. J. Erlandson, *Consultant*----- 692

A Novel Software GNSS Receiver Architecture Using Partial Down-Conversion

S-H. Im, G-I. Jee, *Konkuk University, South Korea*; S-D. Cho, S-J. Ko, *Samsung Electro-Mechanics, South Korea*----- 702

FPGA-Based Architecture for High Throughput, Flexible and Compact Real-Time GNSS Software Defined Receiver

B. Sauriol, R. Landry, *Ecole de Technologie Supérieure, Canada*----- 708

Session C6: MEMS and Inertial Systems

Honeywell Gun-hard Inertial Measurement Unit (IMU) Development

D. Karnick, T. Troske, M. Secord, T. Hanson, T. Braman, D. MacGugan, *Honeywell Defense & Space*; T. Kourepenis, *Draper Laboratories*----- 718

MEMS for Aerospace Navigation

J. Leclerc, *Thales Avionics, France* ----- 725

A Unit Quaternion and Fuzzy Logic Approach to Attitude Estimation

K. Narayanan, M.E. Greene, *Auburn University* ----- 731

Robustness Improvement of a Low Cost MEMS-based GPS/INS, Micro-GAIA

T. Fujiwara, H. Tomita, M. Harigae, *Japan Aerospace Exploration Agency, Japan* ----- 736

Magnetic Heading, Achievements and Prospective

F. Goldenberg, *Goodrich Corporation, ASTC* ----- 743

Sensor Stability of a Low-Cost Attitude Sensor Suitable for Micro Air Vehicles
G.H. Elkaim, C.C. Foster, *University of California - Santa Cruz* ----- 756

Accuracy Degradation of MEMS Integrated Navigation Systems Due to Poorly Aligned Inertial Sensors
Z. Syed, X. Niu, P. Aggarwal, N. El-Sheimy, *The University of Calgary, Canada*----- 771

The DIVA Accelerometer and VIG Gyro: Two Quartz Inertial MEMS for Guidance and Navigation Applications
O. Le Traon, D. Janiaud, S. Masson, S. Muller, M. Pernice, *ONERA , France* ----- 778

Session D1: Urban and Indoor Navigation Technology

Multi-Fault Tolerant RAIM Algorithm for Hybrid GPS/TV Positioning
J-Y. Do, M. Rabinowitz, P. Enge, *Stanford University*----- 788

Development of Indoor Navigation System for a Humanoid Robot Using Multi-Sensors Integration
C.H. Lee, C.G. Park, H.S. Lee, J.G. Lee, *Seoul National University, South Korea*; C.W. Jeon, M.K. Kim, *Soonchunhyang University, South Korea*; W. Kwon, *Samsung Electronics Corporation, South Korea*; Y.M. Yoo, J.I. Kim, G.B. Moon, *Seoul National University, South Korea*----- 798

WPI Precision Personnel Locator System
D. Cyganski, J. Duckworth, S. Makarov, W. Michalson, J. Orr, V. Amendolare, J. Coyne, H. Daempfling, J. Farmer, D. Holl, S. Kulkarni, H. Parikh, B. Woodacre, *Worcester Polytechnic Institute*----- 806

Assessment of GPS Signal Quality in Urban Environments Using Deeply Integrated GPS/IMU
A. Soloviev, D. Bruckner, F. van Graas, *Ohio University*; L. Marti, *Robert Bosch Corporation, RTC* -- 815

Integration of an Inertial Measurement Unit and 3D Imaging Sensor for Urban and Indoor Navigation of Unmanned Vehicles
M. Uijt de Haag, D. Venable, M. Schmearcheck, *Ohio University*----- 829

An Evaluation of the Performance of Various C-SLAM EKF Observation Configurations
M.J. Eilders, *Air Force Research Laboratory*; J. Cloutier, *Independent Contractor, Control Systems Research* ----- 841

Session D2: Carrier-Phase Positioning

Latest Developments in Network RTK Modeling to Support GNSS Modernization
H. Landau, X. Chen, A. Kipka, U. Vollath, *Trimble Terrasat GmbH, Germany*----- 851

Innovative Algorithms to Improve Long Range RTK Reliability and Availability
L. Dai, D. Eslinger, T. Sharpe, *NavCom Technology, Inc.* ----- 860

An Investigation on GPS Receiver Initial Phase Bias and its Determination	
M. Wang, Y. Gao, <i>The University of Calgary, Canada</i> -----	873
Carrier-Phase-Based PPP with Multiple Antennas Based on GR Models	
S. Sugimoto, Y. Kubo, S. Fujita, <i>Ritsumeikan University, Japan</i> -----	881
Unified Positioning Algorithms Based on GNSS Regression Equations – Further Results of Point and Relative Positioning	
Y. Kubo, S. Fujita, S. Sugimoto, <i>Ritsumeikan University, Japan</i> -----	892
Integrity Analysis of Cascade Integer Resolution with Decorrelation Transformations	
P. Henkel, <i>Technische Universität München, Germany</i> ; C. Günther, <i>Deutsches Zentrum Für Luft-und Raumfahrt, (DLR), Germany</i> -----	903
Evaluation of Carrier-Phase Positioning Algorithm by Using On-line RINEX Files From Public Servers	
J. Vargas-Casas, U. Fernández-Plazaola, T.M. Martín-Guerrero, <i>Universidad de Málaga, Spain</i> -----	911
Reducing Carrier Phase Errors with EMD-Wavelet for Precise GPS Positioning	
J. Wang, J. Wang, C. Roberts, <i>University of New South Wales, Australia</i> -----	919
Session D3: Galileo	
Giove-A Navigation and Experimental Payload Design and Operation in Orbit	
E. Rooney, M. Unwin, <i>Surrey Satellite Technology Limited, U.K.</i> ; B. Taylor, <i>University of Surrey, U.K.</i> ; G. Gatti, <i>European Space Agency, The Netherlands</i> -----	929
Galileo GIOVE-A Broadcast E5 Codes and Their Application to Acquisition and Tracking	
G.X. Gao, D.S. De Lorenzo, A. Chen, S.C. Lo, D.M. Akos, T. Walter, P. Enge, <i>Stanford University</i> -----	936
Acquisition of GIOVE-A Signals Using Multi-bit Processing	
J-C. Juang, Y-H. Chen, <i>National Cheng Kung University, Taiwan</i> -----	947
Galileo Receiver Design and Analysis Tool Development in Tampere University of Technology	
J. Raasakka, H. Hurskainen, J. Nurmi, <i>Tampere University of Technology, Finland</i> -----	957
Comparison Between BOC CBOC and TMBOC Tracking	
JJ. Floc'H, M. Soellner, <i>EADS Astrium GmbH, Germany</i> -----	964
Investigation and Experimental Receiving of Galileo Signal	
A. Veitsel, A. Lebedinsky, V. Beloglazov, I. Fomin, <i>Topcon Positioning System, Russia</i> -----	974
SISE Prediction and Iono/Tropo Corrections in a Local Element Augmentation System	
R. Di Corato, S. Falzini, A. Beccarini, <i>Space Engineering S.p.A., Italy</i> ; A. Caporali, C. Morini, T. Pepi, <i>CISAS, University of Padova, Italy</i> -----	979

Session D4: Military Applications

ADAP: Enhancing GPS Protection for NAVWAR

A. Vo, *GPS Wing AFB*; C.R. Falchetti, *U.S. Navy SPAWAR Systems Center*;
A.W. Morrison, SAIC ----- 990

GPS-INS-Radio and GIS Integration into Handheld Computers for Disperse Civilian and Military Urban Operations

P. Labbé, *Canadian Forces Experimentation Centre, Canada*; D. Arden, *Dale Arden Consulting at Defense Research and Development, Canada*; L. Li, *Communications Research Centre, Canada* --- 998

Error Model for SRGPS Ship Reference Point Position Coordinate Estimation

D. Gebre-Egziabher, Y. Shao, *University of Minnesota, Twin Cities* ----- 1011

Research of High Sensitivity GPS Receiver Anti-jamming Using LCMV and Minimum Norm Algorithms Based on Circular Antenna Array

R. Di, *Beijing University of Aeronautics & Astronautics, China*----- 1023

Removing Obsolescence in the 3A GPS Legacy Receiver Through the Application of Current Technologies: A Case Study

C. Raab, *Rockwell Collins Inc.*; J. Parham, *U.S. Air Force*----- 1034

Modernized User Equipment (MUE)

G.C. Fyfe, *USAF, GPS Wing* ----- 1041

Session E1: Atmospheric Effects

Stochastic Modeling of Residual Tropospheric Delay

H.E. Ibrahim, A. El-Rabbany, *Ryerson University, Canada*----- 1044

TEC Estimation and its Validation for Real Time Implementation of Satellite Navigation in GAGAN

S. Sunda, S.M. Regar, S. Shrivastava, *Airports Authority of India, India*; R. Acharya, P.V. Khekale, M.R. Sivaraman, *Space Application Center (ISRO), India* ----- 1050

Foot and Ankle Kinematics During Gait Using Foot Mounted Inertial System

S.P. Kwakkel, S. Godha, G. Lachapelle, *The University of Calgary, Canada*----- 1056

Preliminary Analysis of Ionospheric Delay Variation Effect on GBAS Due to Plasma Bubble at the Southern Region in Japan

T. Yoshihara, N. Fujii, K. Matsunaga, K. Hoshino, T. Sakai, S. Wakabayashi, *Electronic Navigation Research Institute, Japan*----- 1065

Session E2: Emerging Navigation Technologies

Issues and Approaches for Navigation Using Signals of Opportunity

J.F. Raquet, *Air Force Institute of Technology*; M.M. Miller, T.Q. Nguyen, *Air Force Research Laboratory*----- 1073

Manipulating B-Spline Based Paths for Obstacle Avoidance in Autonomous Ground Vehicles

J. Connors, G. Elkaim, *University of California, Santa Cruz* ----- 1081

Tight Coupling of Laser Scanner and Inertial Measurements for a Fully Autonomous Relative Navigation Solution
A. Soloviev, D. Bates, F. van Graas, *Ohio University* ----- 1089

Aerial Vehicle Navigation Over Unknown Terrain Environments Using Flash LADAR and Inertial Measurements
A.K. Vadlamani, M. Uijt de Haag, *Ohio University*----- 1104

Constrained Estimation for GPS/Digital Map Integration
M. Miller, *Air Force Research Laboratory/SNRN*; E. Blasch, *Air Force Research Laboratory/SNAA*;
T. Nguyen, *Air Force Research Laboratory/SNRN*; C. Yang, *Sigtem Technology, Inc.* ----- 1119

Proposal of Navigation Message Format for UAV Pseudolite Navigation System
D. Kim, Y. Yun, B. Park, S. Lee, A. Cho, J. Kim, C. Kee, *Seoul National University, South Korea*--- 1128

Calibrating Non-GPS Navigation Sensors for Use in Robot Localization
M.A. Zmuda, Y.T. Morton, *Miami University* ----- 1137

Flight Testing of a Pseudolite Navigation System on a UAV
J.H.R. Amt, J.F. Raquet, *Air Force Institute of Technology*----- 1147

Session E3: Land-Based and Marine Applications

FDM and FEM Filters in Terrain Navigation
I. Nygren, *TNAV Systems, Sweden*; M. Jansson, *Royal Institute of Technology, Sweden*----- 1155

Differential eLoran Trials in Harwich Harbour
G. Offermans, A. Helwig, *Reelektronika The Netherlands*; P. Williams, *Trinity House U.K.*;
W. Pelgrum, *The Netherlands* ----- 1167

Design and Testing of a GPS Based Track Change Detection System Using Geometry Car Data
H.J. Rome, *Rome Navigation Innovations*; L. Allen, *Federal Railroad Administration* ----- 1179

From the DARPA Grand to Urban Challenge: Mobile Mapping Supporting Autonomous Vehicle Navigation
C. Toth, D.A. Grejner-Brzezinska, U. Ozguner, *The Ohio State University*----- 1196

Navigating Harbors at High Accuracy Without GPS: eLoran Proof-of-Concept on the Thames River
G.W. Johnson, K. Dykstra, C. Oates, *Alion Science & Technology*; P.F. Swaszek, *University of Rhode Island*; R. Hartnett, *U.S. Coast Guard Academy*----- 1201

Towards Ubiquitous Positioning (UbiPos): A GNSS Perspective
X. Meng, A. Dodson, T. Moore, G. Roberts, *University of Nottingham, U.K.* ----- 1212

Session E4: Aviation Applications and Precision Approach

Geometry Screening for GBAS to Meet CAT III Integrity and Continuity Requirements
M. Harris, T. Murphy, *Boeing Commercial Airplanes* ----- 1221

GBAS With RAIM Based on the Constrained GLRT for Precision Landing Using Galileo and GPS

I. Nikiforov, *Universite of Troyes, France*; B. Belabbas, *DLR German Aerospace Center, Germany*; P. Henkel, *Technical University of Munich, Germany*; H. Palcoux, *Ecole Nationale de l'Aviation Civile, France*----- 1234

Fault Detection and Elimination for Galileo-GPS Vertical Guidance

A. Ene, J. Blanch, J.D. Powell, *Stanford University*----- 1244

A New Approach for Computing the Probability of Correct Fix and Integrity Risk for JPALS

S. Draganov, *Argon ST*; D. Smith, G. Johnson, M. Cooper, *ARINC Engineering Services*----- 1255

Vision-only Navigation and Control of Unmanned Aerial Vehicles Using the Sigma-Point Kalman Filter

H. Bai, E. Wan, X. Song, A. Myronenko, *OGI School of Science & Engineering*; A. Bogdanov, *Teledyne Scientific Company*----- 1264

Model Analysis on the Performance for an Inertial Aided FLL-Assisted-PLL Carrier-Tracking Loop in the Presence of Ionospheric Scintillation

T-Y. Chiou, *Stanford University*; D. Gebre-Egziabher, *University of Minnesota, Twin Cities*; T. Walter, P. Enge, *Stanford University*----- 1276

Compliance of Single Frequency Ionospheric Delay Estimation and Cycle Slip Detection with Civil Aviation Requirements

C. Ouzeau, *ENAC/TéSA/DTI, France*; C. Macabiau, A-C. Escher, *ENAC, France*; B. Roturier, *DSNA-DTI, France* ----- 1296