

ION GNSS 2007 Proceedings

Table of Contents

ION GNSS 2007
September 25-28, 2007
Fort Worth, Texas

PLENARY SESSION

Joint Functional Component Command for Space - Precision Navigation and Timing Update

W. Shelton, *Commander, USAF Joint Operations Center* ----- 1

The European GNSS Programmes

P. Pedreira, *Executive Director, European GNSS Supervisory Authority* -----14

Towards a GNSS System of Systems

G.W. Hein, *University FAF Munich, Germany* -----22

Where Have We Been? Where Are We Going?

G. Green, *Navastro* -----31

Session A1: Multi-sensor Navigation, Guidance and Control Systems

Fuzzy Dead Reckoning Algorithm for Personal Navigator

S. Moafipoor, D.A. Grejner-Brzezinska, C.K. Toth, *The Ohio State University* -----48

Separation of Static and Non-Static Features from Three Dimensional Datasets: Supporting Positional Location in GPS Challenged Environments – An Update

J.N. Markiel, D.A. Grejner-Brzezinska, C.K. Toth, *The Ohio State University* -----60

Optimized Low-Cost HSGPS/IMU/WSS Land Vehicle Navigation System for Urban Navigation

M. Spangenberg, *TéSA/Thales Alenia Space, France*; V. Calmettes, *SUPAERO/TéSA, France*;
D. Kubrak, *Thales Alenia Space, France*; O. Julien, *Ecole Nationale de l'Aviation Civile, France* -----70

Tight Integration of Dual ALS and IMU for Autonomous Aerial Vehicle Navigation

A.K. Vadlamani, M. Uijt de Haag, *Ohio University* -----80

Development of a Low Cost Multiple GPS Antenna Attitude System

C. Hide, J. Pinchin, D. Park, *Geospatial Research Centre NZ Ltd., New Zealand* -----88

A Low Cost GPS/INS Sensor for Small UAVs Augmented with Multiple GPS Antennas R. Hirokawa, R. Ohata, <i>Mitsubishi Electric Corporation, Japan</i> ; T. Ebinuma, <i>Tokyo University of Marine Science and Technology, Japan</i> ; T. Suzuki, <i>Waseda University, Japan</i> -----	96
---	----

Integrating DGPS and 3D Gyro Sensor for Tractor Guidance System for Precision Farming Y. Zhang, K. Nii, M. Uchiyama, <i>Geosurf Corporation, Japan</i> ; K. Inoue, <i>National Agriculture Research Center for Hokkaido Region, Japan</i> -----	104
---	-----

An Investigation of an Integrated Low-cost GPS, INS and Magnetometer System for Sport Applications F. Wu, K. Zhang, M. Zhu, <i>RMIT University, Australia</i> ; C. Mackintosh, T. Rice, C. Gore, A. Hahn, <i>Australian Institute of Sport, Australia</i> ; S. Holthous, <i>Catapult Innovations Pty. Ltd., Australia</i> -----	113
--	-----

FPGA Implementation of High Resolution Spectral De-Noiseing Modules of MEMS - based Inertial Sensors S. Dybwad, D. McGaughey, A. Noureldin, <i>Royal Military College of Canada</i> -----	121
---	-----

An Efficient UKF Based GPS/INS Augmented by Local Landmark Update R. Hirokawa, K. Nakakuki, <i>Mitsubishi Electric Corporation, Japan</i> -----	127
---	-----

Exploiting Network Real-time Kinematic GNSS Positioning for Transport Applications X. Meng, A. Dodson, T. Moore, <i>The University of Nottingham, UK</i> ; C. Liu, <i>Tongji University, China</i> ; P. Cheng, Q. Wang, C. Li, <i>Chinese Academy of Surveying and Mapping, China</i> -----	135
---	-----

Session B1: Military Applications

Real-Time Software Based Block Processing M-code Receiver A. Jovancevic, S. Ganguly, B. Sirpatil, M. Kirchner, S. Zigic, <i>Center for Remote Sensing, Inc.</i> -----	142
---	-----

Long-Term Prediction of GPS Accuracy: Understanding the Fundamentals T. Driver, <i>Analytical Graphics Inc.</i> -----	152
---	-----

Development of an Anti-Jamming System Using Available Antennas D. Wilson, S. Ganguly, <i>Center for Remote Sensing, Inc.</i> -----	164
--	-----

Analysis of GPS Monitor Station Outages B.J. Stanton, R. Strother, <i>SI International, Inc., HQ Air Force Space Command</i> -----	176
--	-----

GPS as an Enabling Technology Supporting Autonomous Ocean Deployed Craft J. Copeland, D. Tucker, <i>Applied Research Laboratories</i> -----	184
---	-----

Session C1: GNSS Receiver Algorithms 1

Enhanced Differential Detection Scheme for Weak GPS Signal Acquisition S.K. Shanmugam, J. Nielsen, G. Lachapelle, <i>University of Calgary, Canada</i> -----	189
--	-----

An Innovative Acquisition Method for the GPS and Galileo Combined Signal Y-C. Lin, C-C. Sun, <i>National Cheng Kung University, Taiwan</i> -----	203
--	-----

Acquisition Performance of Assisted and Unassisted GNSS Receivers with New Satellite Signal	
S. Turunen, <i>Nokia Corporation, Finland</i> -----	211
A Novel L1 and L2C Combined Detection Scheme for Enhanced GPS Acquisition	
C. Gernot, S.K. Shanmugam, K. O'Keefe, G. Lachapelle, <i>University of Calgary, Canada</i> -----	219
A New GNSS Software Receiver Signal Acquisition Method Research Based on Ambiguity Function	
J. Guo, W. Wang, B. Chao, <i>Wuhan University, China</i> -----	231
Post Correlation CWI and Cross Correlation Mitigation Using Delayed PIC	
E.P. Glennon, R.C. Bryant, <i>SigNav Pty Ltd., Australia</i> ; A.G. Dempster, P.J. Mumford, <i>University of New South Wales, Australia</i> -----	236
Tracking L1 C/A and L2C Signals Through Ionospheric Scintillations	
M.L. Psiaki, T.E. Humphreys, A.P. Cerruti, S.P. Powell, P.M. Kintner, <i>Cornell University</i> -----	246
Looking for an Optimum S-Curve Shaping of the Different MBOC Implementations	
M. Paonni, J.A. Avila-Rodriguez, T. Pany, G.W. Hein, B. Eissfeller, <i>University FAF Munich, Germany</i> -----	269
A Simple Technique for the Detection of Multiple Access Interference in the Parallel Acquisition of Weak GPS Signals	
C. O'Driscoll, <i>University of Calgary, Canada</i> ; C.C. Murphy, <i>University College Cork, Ireland</i> -----	282
A Complete GPS Signal Processing for Real Time Scenario	
N. Sonowal, R. Yadav, <i>Centre for Air-Borne Systems, India</i> -----	292
Session D1: Algorithms and Methods 1	
The Optimal Regularization Method and its Application in GNSS Rapid Static Positioning	
J. Cai, <i>University of Stuttgart, Germany</i> ; C. Hu, <i>Tongji University, China</i> ; E.W. Grafarend, <i>University of Stuttgart, Germany</i> -----	299
Statistical Error Calibration for Hatch-filtered Ranges using Spectral Characterization of Raw Measurement Errors	
J. Mach, I. Deuster, R. Wolf, <i>IfEN GmbH, Germany</i> -----	306
Partial Ambiguity Fixing within Multiple Frequencies and Systems	
W. Cao, K. O'Keefe, M.E. Cannon, <i>University of Calgary, Canada</i> -----	312
Dynamic Model Independent Float Filter Architecture Based on Triple Differences	
A. Sasse, U. Bestmann, M. Steen, M. Becker, P. Hecker, <i>Technical University of Braunschweig, Germany</i> -----	324
The Statistical Property of the GNSS Carrier Phase Observations and its Effects on the Hypothesis Testing of the Related Estimators	
J. Cai, E.W. Grafarend, <i>University of Stuttgart, Germany</i> ; C. Hu, <i>Tongji University, China</i> -----	331

Reliable Multi-Carrier Ambiguity Resolution in the Presence of Multipath
S. Verhagen, D. Odijk, *Delft University of Technology, The Netherlands*; F. Boon,
Septentrio Satellite Navigation, Belgium; J.M. Lopez Almansa, *GMV, Spain* ----- 339

Flying™ RTK Solution as Effective Enhancement of Conventional Float RTK
D. Kozlov, G. Zyryanov, *Magellan, Russia* ----- 351

Coarse-Time AGPS; Computing TOW From Pseudorange Measurements, and the Effect on HDOP
F. van Diggelen, C. Abraham, *Broadcom Corporation* ----- 357

Session E1: GNSS Ground Based Augmentation Systems

Design of a Single-Frequency Filter that Minimizes Ionosphere Divergence Error
J. Rife, S. Sen, *Tufts University* ----- 368

Initial Design and Performance Results of the University of Oklahoma LAAS Far-Field Monitor
C. Davis, A. Archinal, J. Dyer, H. Wen, J. Fagan, *University of Oklahoma* ----- 379

Ephemeris Failure Rate Analysis and its Impact on Category I LAAS Integrity
L. Gratton, R. Pramanik, H. Tang, B. Pervan, *Illinois Institute of Technology* ----- 386

A Safety Hazard Analysis Method for Category-I Ground Based Augmentation System
J. Burns, *Federal Aviation Administration*; D. Guenter, *Innovative Solutions International*;
E. Altshuler, *Sequoia Inc.* ----- 395

Data-Replay Analysis of LAAS Safety During Ionosphere Storms
Y.S. Park, G. Zhang, S. Pullen, Y. Lee, P. Enge, *Stanford University* ----- 404

Advanced GPS Performance Monitor
Z. Zhu, S. Gunawardena, M. Uijt de Haag, F. van Graas, *Ohio University* ----- 415

Dual-Frequency Smoothing for CAT III LAAS: Performance Assessment Considering Ionosphere Anomalies
H. Konno, *Stanford University* ----- 424

More Ionosphere Anomaly Mitigation Considerations for Cat II/III GBAS
T. Murphy, M. Harris, *Boeing Commercial Airplanes* ----- 438

A Concept of CAT III GBAS Requirement Based on Real-time Flight Technical Error Estimation
N. Fujii, *Electronic Navigation Research Institute (ENR), Japan* ----- 453

Conceptualization and Implementation of a Closed-Loop Ground Based Augmentation System
C. Davis, J. Dyer, A. Archinal, H. Wen, J. Fagan, *University of Oklahoma* ----- 461

Session F1: Galileo System Design and Services

GIOVE-A in Orbit Testing Results
E. Rooney, M. Unwin, *Surrey Satellite Technology Ltd., UK*; G. Gatti, M. Falcone, S. Binda,
M. Malik, D. Hannes, *European Space Agency, The Netherlands* ----- 467

An Incremental System Approach to GALILEO In-Orbit Validation	
M. Falcone, E. Breeuwer, <i>European Space Agency, The Netherlands</i> -----	478
Characterization of the Navigation Performances in Galileo: E-OSPF SW Experimentation Results	
A.B. Martín Peiró, M.D. Laínez, P.F. Navarro, J.R. Martín, A. Gavín, <i>GMV, Spain</i> ; F. Amarillo, A. Ballereau, B. Schlarmann, <i>ESA, Galileo Project Office</i> -----	488
Preliminary Design of the Galileo Mission Support Facility (MSF)	
M. Sánchez-Gestido, A. Ramírez-Jiménez, F. Bertrand, A.I. Mediavilla, O. Bellido-Tirado, P. Falconio, <i>Deimos-Space, S.L., Spain</i> ; P. Claes, <i>European Space Agency</i> -----	500
Galileo Payload Test System - The Receiver Subsystem	
J. Winkel, T. Lück, M. Bodenbach, E. Göhler, N. Falk, <i>IfEN GmbH, Germany</i> ; H. Wolf, H. Kubr, <i>Siemens Austria</i> ; L. Minelli, <i>Astrium, UK</i> -----	509
A Vision on New Frequencies, Signals and Concepts for Future GNSS Systems	
J.A. Avila-Rodriguez, S. Wallner, G.W. Hein, B. Eissfeller, <i>University FAF Munich, Germany</i> ; M. Irsigler, <i>IfEN GmbH, Germany</i> ; J-L. Issler, <i>CNES, France</i> -----	517
SEA GATE - A Maritime Galileo Testbed in the Port of Rostock	
S. Martin, H. Kuhlen, S. Schlötzer, A. Schmitz-Peiffer, M. v. Voithenberg, <i>EADS Astrium, Germany</i> ; H. Dietz, <i>EADS RST, Germany</i> -----	535
The Effects of I/Q Imbalance and Complex Filter Mismatch on GPS/Galileo System	
P-H. Lee, H-C. Chao, <i>National Taiwan University, Taiwan</i> ; W-L. Mao, <i>National Formosa University, Taiwan</i> ; H-W. Tsao, F-R. Chang, <i>National Taiwan University, Taiwan</i> -----	543
Session A2: Algorithms for Multi-sensor Fusion	
A New Federated Kalman Filter for Integrated Navigation Systems Based on SINS	
D. Gu, <i>The University of Calgary, Canada</i> ; Y. Qin, <i>Northwestern Polytechnical University, China</i> ; N. El-Sheimy, <i>The University of Calgary, Canada</i> -----	551
Gaussian Mixture Filters and Hybrid Positioning	
S. Ali-Löytty, N. Sirola, <i>Tampere University of Technology, Finland</i> -----	562
Improving Adaptive Kalman Filter in GPS/SDINS Integration with Neural Network	
J.J. Wang, W. Ding, J. Wang, <i>University of New South Wales, Australia</i> -----	571
Hybrid A-GPS and Ranging for Handset Positioning	
N. Harper, M. Dawson, <i>Andrew Corporation, Australia</i> -----	579
Multi-Sensor Integration for Autonomous Vehicle Relative Navigation	
A. Vydhyanathan, M.S. Braasch, M. Uijt de Haag, <i>Ohio University</i> -----	587
New Approaches for Accuracy Enhancement of MEMS Based INS Integrated with GPS for Land Vehicles	
A. Noureldin, D. McGaughey, M. Eberts, C. Johnston, <i>Royal Military College of Canada</i> -----	596

Performance Analysis of an Ultra-Tightly Integrated GPS and Reduced IMU System
M.G. Petovello, D. Sun, G. Lachapelle, M.E. Cannon, *The University of Calgary, Canada* ----- 602

Improving GPS Location Availability and Reliability by Using a Suboptimal, Low-cost MEMS Sensor Set
M. Chowdhary, J. Colley, M. Chansarkar, *SiRF Technology, Inc.*----- 610

The AI Based Compensators for a Rapid and Accurate Alignment Procedure: An Open Loop Approach
Y-W. Huang, K-W. Chiang, *National Cheng-Kung University, Taiwan*----- 615

Session B2: Network-Based RTK

Generating VRS Data Using Atmospheric Models: How Far Can We Go?
D.B.M. Alves, J.F.G. Monico, L.F.A. Dalbello, *São Paulo State University, Brazil*;
L.F. Sapucci, *CPTEC-INPE, Brazil*----- 626

Application of Predicted Ionosphere Model to Medium Range RTK Positioning: Performance Assessment
P. Wielgosz, A. Krankowski, L.W. Baran, *University of Warmia and Mazury, Poland*;
D. Grejner-Brzezinska, *The Ohio State University* ----- 634

Long-Range Single-Baseline RTK for Complementing Network-Based RTK
D. Kim, R.B. Langley, *University of New Brunswick, Canada*----- 639

Undifferenced Ionosphere and Troposphere Estimation for Network Kinematic GPS
P.M. Grgich, *The University of Melbourne, Australia* ----- 651

Joint GPS/GALILEO Precise Positioning Performance Using Active Reference Networks
E. Schueler, T. Schueler, B. Eissfeller, *University FAF Munich, Germany*----- 661

Multiple Carrier Ambiguity Resolution and Performance Benefits for RTK and PPP Positioning Services in Regional Areas
Y. Feng, *Queensland University of Technology, Australia*; C. Rizos, *University of New South Wales, Australia*; M. Higgins, *Queensland Government, Australia*----- 668

Novel Concept in Multiple GNSS Network RTK Processing
H-J. Euler, *inPosition GmbH, Switzerland*; J. Wirth, *HSR Hochschule fuer Technik Rapperswil, Switzerland* ----- 679

Data Quality and Coordinate Monitoring for a Permanent Network: Proposals and Experiences
L. Biagi, S. Caldera, M.G. Visconti, *Polytechnic of Milano, Italy*----- 687

The Latest Development of a State-wide GNSS Network-based RTK System in Australia
K. Zhang, F. Wu, S. Wu, *RMIT University, Australia*; C. Rizos, S. Lim, C. Roberts, L. Ge, *University of New South Wales, Australia*; A. Kealy, *The University of Melbourne, Australia*----- 699

Session C2: GNSS Receiver Algorithms 2

Theory and Applications of Signal Compression in GNSS Receivers
L.R. Weill, *California State University, Fullerton / Comm Sciences Corporation* ----- 708

A Modified Adaptive Bandwidth Algorithm for Robust Optimal Signal Tracking of DGPS Reference Receiver	
S.H. Park, D.J. Cho, S.H. Suh, <i>Korea Ocean Research and Development Institute, South Korea</i> ; D.W. Lim, S.J. Lee, <i>Chungnam National University, South Korea</i> -----	720
Direction of Arrival Estimation of GNSS Signals Based on Synthetic Antenna Array	
A. Broumandan, T. Lin, A. Moghaddam, D. Lu, J. Nielsen, G. Lachapelle, <i>The University of Calgary, Canada</i> -----	728
On the Probability Density Function and Stability Properties for a Cross-Product Frequency-Locked Loop	
T-Y. Chiou, <i>Stanford University</i> -----	739
Performance Evaluation of Kalman Filter Based Tracking for the New GPS L5 Signal	
C. Mongredien, M.E. Cannon, G. Lachapelle, <i>The University of Calgary, Canada</i> -----	749
Optimal Code and Carrier Tracking Loop Design of Galileo BOC(1,1)	
G-I. Jee, S-H. Im, B-H. Lee, <i>Konkuk University, South Korea</i> -----	759
Subcarrier Tracking Performances of BOC, ALTBOC and MBOC Signals	
A. de Latour, T. Grellier, G. Artaud, L. Ries, J-C. Issler, <i>CNES, France</i> ; V. Heiries, <i>Thales Alenia Space, France</i> -----	769
Optimised Lock Detection Strategy Using BOC Correlator Outputs	
J. Diez, <i>DEIMOS Space, Spain</i> ; J.S. Silva, <i>DEIMOS Engenharia, Portugal</i> ; A. Fernández, <i>DEIMOS Space, Spain</i> -----	782
Comparison of Traditional Tracking Loops and Vector Based Tracking Loops for Weak GPS Signals	
M. Lashley, <i>Navigation Technology Associates</i> ; D.M. Bevly, <i>Auburn University</i> -----	789
Equivalence Principle of GPS Algorithms and an Independent Parameterisation Method	
G. Xu, <i>GeoForschungsZentrum Potsdam, Germany</i> ; Y. Yang, <i>Institute of Surveying & Mapping</i> ; H. Sun, <i>Institute of Geodesy & Geophysics</i> ; Y. Shen, <i>Tongji University</i> ; Q. Zhang, <i>ChangAn University</i> ; J. Guo, <i>Information Engineering University</i> ; T-K. Yeh, <i>Ching Yun University, Taiwan</i> -----	796
Session D2: Algorithms and Methods 2	
Investigation of Instantaneous Ambiguity Resolution with the GPS/Galileo Combination for Precise Kinematic Positioning	
D.B. Morujão, <i>Universidade de Lisboa, Portugal</i> ; V.B. Mendes, <i>Instituto Dom Luis / Universidade de Lisboa, Portugal</i> -----	808
Implementation of a Least Mean Square Approach for a Low-Cost Short Baseline Attitude Determination	
N. Parikh, <i>NavCom Technology</i> ; A. Soloviev, F. van Graas, <i>Ohio University</i> -----	818
Two Approaches to Precise Kinematic GPS Positioning with Miniaturized L1 Receivers	
D. Odijk, <i>Delft University of Technology, The Netherlands</i> ; J. Traugott, G. Sachs, <i>Technical University of Munich, Germany</i> ; O. Montenbruck, <i>German Space Operations Center, Germany</i> ; C. Tiberius, <i>Delft University of Technology, The Netherlands</i> -----	827

Integer Ambiguity Resolution on Undifferenced GPS Phase Measurements and its Application to PPP	
D. Laurichesse, F. Mercier, <i>CNES, France</i> -----	839
Constrained Kalman Filter Based Attitude Estimation with GPS Signals	
J.G. García, P.A. Roncagliolo, C.H. Muravchik, <i>Universidad Nacional de La Plata, Argentina</i> -----	849
Performance Analysis of Precise Point Positioning Based on Combined GPS and GLONASS	
C. Cai, Y. Gao, <i>University of Calgary, Canada</i> -----	858
Combined Processing of GPS, GLONASS, and SBAS Code Phase and Carrier Phase Measurements	
L. Wanninger, S. Wallstab-Freitag, <i>Dresden University of Technology, Germany</i> -----	866
The Contribution of GLONASS and GALILEO to Kinematic GPS Precise Point Positioning	
J.G.O. Gjevestad, O. Øvstedal, <i>Norwegian University of Life Sciences, Norway</i> ; N.S. Kjørsvik, <i>TerraTec AS, Norway</i> -----	876
Performance Evaluation of Single Antenna GPS Attitude Algorithms with the Aid of Future GNSS Constellations	
C. Wang, R.A. Walker, Y. Feng, <i>Queensland University of Technology, Australia</i> -----	883
Session E2: GNSS Space Based Augmentation Systems	
Wide Area Augmentation System (WAAS) - Program Status	
D. Lawrence, D. Bunce, <i>Federal Aviation Administration</i> ; N.G. Mathur, <i>AMTI</i> ; C. Edward Sigler, <i>Sigler and Associates</i> -----	892
The Qualification of EGNOS, the Final Step to the Operational Service	
U. Guida, M. Vritschan, J. Westbrook, <i>European Satellite Services Provider, Belgium</i> -----	900
GNSS Performance Monitoring Services with GalTeC	
W. Ehret, H. Su, O. Glaser, A. Wahl, <i>Thales, Germany</i> ; E. Blomenhofer, <i>NavPos Systems, Germany</i> -----	907
EGNOS Protection on Two GPS Clock Events	
J. Maréchal, N. Suard, <i>CNES, France</i> ; D. Chinchilla, <i>Technical University of Catalonia</i> -----	919
Mitigating Ionospheric Threat Using Dense Monitoring Network	
T. Sakai, K. Matsunaga, K. Hoshinoo, K. Ito, <i>Electronic Navigation Research Institute, Japan</i> ; T. Walter, <i>Stanford University</i> -----	927
The Usefulness of WADGPS Satellite Orbit and Clock Corrections for Dual-Frequency Precise Point Positioning	
H. Rho, R.B. Langley, <i>University of New Brunswick, Canada</i> -----	939
SBAS C/A Code Interferences: Observations and Induced Tracking Errors	
O. Nouvel, M. Sihrener, <i>M3Systems, France</i> ; J.L. Issler, L. Lestarquit, <i>CNES, France</i> ; C. Macabiau, O. Julien, <i>ENAC, France</i> -----	950

Performance Analysis of GPS Augmentation Using Future Taiwanese SBAS
Y-S. Huang, Y-W. Huang, K-W. Chiang, M. Yang, *National Cheng-Kung University, Taiwan*----- 960

Development of a Multi-constellation Augmentation Service Based on EGNOS and Galileo Simulation
R. Chen, *Finnish Geodetic Institute, Finland*; C. Hill, T. Moore, *University of Nottingham, UK*;
P. Cheng, *Chinese Academy of Surveying & Mapping, China*; L. Yang, *University of Nottingham, UK*;
E. Guyader, *European GNSS Supervisory Authorities*; Y. Chen, A. Hyttinen, *Finnish Geodetic Institute, Finland*; Y. Cai, *Chinese Academy of Surveying and Mapping, China*----- 966

The European Space Agency Free Resources for SBAS Education: Learning, Practising, and Accessing the EGNOS Performances in Real-Time
F. Torán, J. Ventura-Traveset, C. López, A.R. Mathur, P. Pintor, *EGNOS Project Office, ESA, France*; M. Houdek, P. Bares, *Iguassu Software Systems, Czech Republic* ----- 976

WAAS Utilization of the New Civil Signal at L2
S-S. Jan, *National Cheng Kung University, Taiwan*----- 984

Session F2: Galileo and GPS/Galileo Reference and User Receiver

An Adaptive Approach to Compensate Crosscorrelation Effects in Weak Signal Conditions for Satellite Positioning Systems
C. Lacatus, D. Akopian, M. Shadaram, *University of Texas at San Antonio*----- 990

Multiresolution Acquisition Engine Tailored to the Galileo AltBOC Signals
F. Dovis, *Politecnico di Torino, Italy*; P. Mulassano, *Instituto Superiore Mario Boella, Italy*;
D. Margaria, *Politecnico di Torino, Italy* ----- 999

Artus - A Second Generation Galileo/GPS Receiver
T. Lueck, J. Winkel, M. Bodenbach, E. Göhler, N. Falk. *IfEN GmbH, Germany*;
A. Consoli, F. Piazza, D. Gerna, *Nemerix, Switzerland*; R. Granger, P. Reedman,
S. Simpson, *Roke Manor Research, UK*; H-J. Euler, *inPosition GmbH, Switzerland* ----- 1008

The Optimal Dual Estimate Solution for Robust Tracking of Binary Offset Carrier (BOC) Modulation
M.S. Hodgart, P.D. Blunt, *University of Surrey, UK*; M. Unwin, *Surrey Satellite Technology, Ltd., UK*----- 1017

GIOVE Mission Sensor Station Performance Characterization: Overview of the Results
M. Crisci, M. Hollreiser, M. Falcone, M. Colina, *European Space Agency, The Netherlands*;
J. Giraud, *Thales Alenia Space, France* ----- 1028

Indoor Galileo Receivers — Sensitivity, Pilot Signals, Secondary Codes
P.G. Mattos, *STMicroelectronics R&D Ltd., UK* ----- 1042

ORUS Galileo/GPS Open Receiver
F. Benghouzi, *M3 Systems, France*; J.P. Gisbert, *ESTEC, France*; J-L. Issler, *CNES, France* ----- 1049

Galileo Receiver Chain - The nonPRS Ground Reference Receiver
N. Gerein, A. Manz, *NovAtel Inc., Canada*; G. Pinelli, G. Franzoni, A. Zin,
Thales Alenia Space, Italia ----- 1054

The BayNavTech™ Signal Experimentation Facility (BaySEF™) is Ready for Assessing GNSS Signal Performance

M. Soellner, C. Briechle, G. Hechenblaikner, M. Kaindl, R. Kohl, W. Lindemer, M. Middendorf, C. Zecha, *EADS Astrium, Germany* ----- 1065

A Second-Order-BPSK-like(SOB) Method for the Acquisition of BOC(1,1)

L. Yang, C. Jiapin, L. Zhenbo, *Shanghai JiaoTong University, China*; C. Nongji, *Mitsubishi Electric ITE-VIL, China* ----- 1073

Preliminary Results of the Canadian Galileo Safety of Life Receiver (SOLRX)

M. Bates, *NovAtel Inc., Canada*; H. Saaied, *Easterline/CMC Electronics, Canada*; M. Olynik, *NovAtel Inc., Canada*; B. Van Wyck, *Easterline/CMC Electronics, Canada*; N. Gerein, *NovAtel Inc., Canada*; Y. Blondeau, J. Studenny, *Easterline/CMC Electronics, Canada* ----- 1079

Session A3: Alternatives and Backups to GNSS

Gravity Gradiometer Aided Inertial Navigation Within Non-GNSS Environments

J.A. Richeson, *University of Maryland*----- 1089

Beacon-Loran Integrated Navigation Concept (BLINC): An Integrated Medium Frequency Ranging System

G.W. Johnson, C. Oates, M. Wiggins, *Alion Science & Technology*; P.F. Swaszek, *University of Rhode Island*; R. Hartnett, *US Coast Guard Academy* ----- 1101

Flight Test Results of a Video-Aided GPS/Inertial Navigation System

Alison Brown, B. Bockius, B. Johnson, H. Holland, D. Wetlesen, *NAVSYS Corporation*----- 1111

Research Activities on Locata Technology at the University of New South Wales

N. Politi, *University of New South Wales, Australia*; J. Barnes, *Locata Corporation Pty Ltd., Australia*; C. Rizos, A. Dempster, *University of New South Wales, Australia*; N. Tambuwala, M. Jamal, *University of Melbourne, Australia*----- 1118

End-to-End Testing of an Integrated Centimetric Positioning Test-Bed

T. Moore, C. Hill, S. Ince, *University of Nottingham, UK*; W. Ochieng, S. Feng, *Imperial College London, UK*; R. Ioannides, *University of Leeds, UK*; P. Cross, L. Lau, *University College London, UK*----- 1128

Evaluating Measurement-Based AOA Indoor Location using WLAN Infrastructure

C.M. Wong, *University of British Columbia, Canada*; G.G. Messier, *University of Calgary, Canada*; R. Klukas, *University of British Columbia, Canada*----- 1139

Security Analysis of Geoencryption: A Case Study Using Loran

Di Qiu, *Stanford University* ----- 1146

Integration of RFID, GNSS and DR for Ubiquitous Positioning in Pedestrian Navigation

G. Retscher, Q. Fu, *Vienna University of Technology, Austria* ----- 1155

Session B3a: GNSS Civil Interference and Spectrum Aspects

GNSS Interference Detection and Localization using a Network of Low Cost Front-End Modules

J. Lindström, D.M. Akos, O. Isoz, M. Junered, *Luleå University of Technology, Sweden*----- 1165

Code Acquisition with Interference Mitigation for Galileo Receivers
C. Palestini, R. Pedone, M. Villanti, G.E. Corazza, *DEIS/ARCES, University of Bologna, Italy* ----- 1173

Mutual Effects of Satellite Signal Quality and Satellite Geometry on Positioning Quality
A.T. Balaei, B. Motella, A.G Dempster, *University of New South Wales, Australia* ----- 1182

DME/TACAN Interference and its Mitigation in L5/E5 Bands
G.X. Gao, *Stanford University* ----- 1191

Radio Frequency Compatibility Criterion for Code Tracking Performance
F. Soualle, *EADS-Astrium, Germany*; T. Burger, *ESA, The Netherlands* ----- 1201

Interference Monitoring for GNSS Bands in Indoor and Urban Environments
M. Adjrad, *University of Leeds, UK*; L.E. Aguado, *Advanced Digital Institute*; M. Daly, A. Kemp, *University of Leeds, UK*; M. Junered, J. Lindström, D. Akos, *Luleå University of Technology, Sweden*; F. Mangin, *France Developpement Conseil* ----- 1211

Session B3b: GNSS Antenna and Radio Technology

Mitigation of GPS Multipath Using Polarization and Spatial Diversities
M. Brenneman, J. Morton, *Miami University*; C. Yang, *Sigtem Technology, Inc.*; F. van Graas, *Ohio University* ----- 1221

GNSS Receiver Biases Due to Non-Linear Phase of Contolled Pattern and Fixed Pattern Antennas
C.M. Church, I.J. Gupta, *The Ohio State University* ----- 1230

GPS Block II/IIA Satellite Antenna Testing Using the Automated Absolute Field Calibration with Robot
G. Wübbena, M. Schmitz, *Geo++*, *Gesellschaft fur gatellitengestutzte geodatische und Navigatorische Technologien mbH, Germany*; G. Mader, *National Geodetic Survey, NOS/NOAA*; F. Czopek, *Boeing Company* ----- 1236

Receiver Processing Losses with Bandlimiting and One-Bit Sampling
J.W. Betz, N.R. Shnidman, *The MITRE Corporation* ----- 1244

Sequential Interference Nulling and Localization in Two-Dimensional GPS Receiver Array
M.G. Amin, *Villanova University*----- 1257

Session C3: New Product Announcements

Advanced Family of Software Simulators
A. Brown, S. Ganguly, *Center for Remote Sensing, Inc.* ----- 1265

Continuous Data Storage and Replay Unit
S. Ganguly, S. Zigic, *Center for Remote Sensing, Inc.* ----- 1277

The GPSTk: New Features, Applications, and Changes
R.B. Harris, T. Conn, T. Gaussiran, C. Kieschnick, J. Little, R. Mach, D. Munton, B. Renfro, S. Nelsen, B. Tolman, J. Vorce, *The University of Texas at Austin*; D. Salazar, *Universitat Politecnica de Catalunya, Spain* ----- 1286

GNSS Signal Generator NSG 5100 S. Martin, S. Diefenbach, D. Felbach, S. Schloetzer, M. v. Voithenberg, <i>EADS Astrium, Germany</i> -----	1297
BayNavTech - Performance Assessment Facility for GNSS J. Vilzmann, M. Kirchner, C. Schäfer, <i>EADS Astrium, Germany</i> -----	1304
Mm Level Precision in Ionospheric GPS Measurements L. Dyrud, A. Jovancevic, S. Ganguly, <i>Center for Remote Sensing, Inc.</i> -----	1312
NavX®-NCS - The First Galileo/GPS Full RF Navigation Constellation Simulator G. Heinrichs, M. Irsigler, R. Wolf, J. Winkel, <i>IfEN GmbH, Germany</i> ; G. Prokoph, <i>Work Microwave GmbH, Germany</i> -----	1323
NavX®-NSR - A Novel Galileo/GPS Navigation Software Receiver G. Heinrichs, M. Restle, C. Dreischer, <i>IfEN GmbH, Germany</i> ; T. Pany, <i>University FAF Munich, Germany</i> -----	1329
Novel Medium-accuracy MEMS INS "AIST-320" - Building Comfort Environment for Sensors O. Mezentsev, E. Frolov, M. Klimkin, A. Mezentsev, <i>i-SENSE LLC, Russia</i> -----	1335
Hammerhead II – The World’s Smallest GPS Receiver J. de Salas, C. Abraham, R. Najarian, <i>Global Locate, Inc.</i> (Not available for Publication) -----	
A Set of High Accuracy Low Cost Metallic Resonator CVG V.V. Chikovani, Y.A. Yatsenko, A.S. Barabashov, V.A. Kovalenko, P. Tewksbury, <i>Innalabs Holding Inc., Ukraine</i> -----	1345
Session D3: Indoor Positioning 1	
Performance Assessment of Almanac Navigation T. Jokitalo, H. Kuusniemi, S. Söderholm, S. Kakarlapudi, <i>Fastrax Ltd., Finland</i> -----	1351
Robust GPS Receiver for Indoor Navigation System by Utilizing Long Integration Time and Data-less Pseudolite T. Lee, <i>Seoul National University, South Korea</i> -----	1359
Apples to Apples: A Standardized Testing Methodology For High Sensitivity GNSS Receivers A. Mitelman, P-L. Normark, M. Reidevall, S. Strickland, <i>Cambridge Silicon Radio, Sweden</i> -----	1370
A Pedestrian Navigation System for Urban and Indoor Environments F. Weimann, G. Abwerzger, <i>TeleConsult Austria GmbH, Austria</i> ; B. Hofmann-Wellenhof, <i>TeleConsult Austria GmbH/Graz University of Technology, Austria</i> -----	1380
A Novel Efficient Acquisition Scheme for a High Sensitivity Assisted GPS Receiver Z. Liu, <i>University of Tokyo, Japan</i> ; C. Fan, <i>Tokyo University of Marine Science & Technology, Japan</i> ; S. Asano, <i>University of Tokyo, Japan</i> ; N. Kishimoto, <i>Magellan Systems Japan, Inc., Japan</i> ; H. Hojo, A. Yasuda, <i>Tokyo University of Marine Science and Technology, Japan</i> -----	1390

Implementation of an Optimized Code Loop for Indoor Positioning
N. Jardak, A. Vervisch-Picois, *GET/INT, France*; M. Jeannot, *CNES, France*;
A. Fluerasu, N. Samama, *GET/INT, France* ----- 1396

Obtaining a Faster and More Accurate First Position Fix in Poor Signal Environments
H. Kuusniemi, T. Jokitalo, S. Söderholm, S. Kakarlapudi, *Fastrax Ltd., Finland* ----- 1405

High Precision Ranging Using Temporal TDOA and Multipath Tracking in the Absence of Direct Path
F.O. Akgül, K. Pahlavan, *Worcester Polytechnic Institute* ----- 1413

Study of Multipath Effects for the GNSS Repeater Based Indoor Positioning Technique
A. Fluerasu, N. Jardak, A. Vervisch-Picois, *GET/INT, France*; M. Jeannot, M. Boschetti,
CNES, France; N. Samama, *GET/INT, France* ----- 1418

WPI Precision Personnel Locator System - Evaluation by First Responders
J. Duckworth, D. Cyganski, S. Makarov, W. Michalson, J. Orr, V. Amendolare,
J. Coyne, H. Daempfling, D. Hubelbank, H. Parikh, B. Woodacre,
Worcester Polytechnic Institute ----- 1427

Session E3: Land Applications

GNSS Messaging Scheme for Vehicle-to-Vehicle (V2V) and Vehicle-to-Infrastructure (V2I) Communications Based Precise Positioning with Low-Cost GNSS Hardware
C. Basnayake, *General Motors Research and Development Center* ----- 1436

Instantaneous RTK Positioning with Altitude-aiding for ITS Applications
N. Kubo, A. Yasuda, *Tokyo University of Marine Science and Technology, Japan* ----- 1447

Improving Positioning Accuracy and Integrity in Rail Safety-Critical Applications Through the Integration of GNSS with a Track Data Base
Y. Zheng, *University College London, UK* ----- 1456

Development of a GNSS Odometer
A. Wieser, *Graz University of Technology, Austria* ----- 1466

Smart Pseudolites Array System using Two-way Pseudolites
T. Lee, H. So, K. Kim, C. Kee, *Seoul National University, South Korea* ----- 1477

Experimental Results for Spline Based Obstacle Avoidance of an Off-Road Ground Vehicle
J. Connors, G.H. Elkaim, *University of California, Santa Cruz* ----- 1484

A Continuous Updating Technique for Loosely Coupled RTK GPS with Total Station Observations
A. Taha, *The University of Nottingham, UK* ----- 1491

Hybrid GNSS Receiver for Super Fast Acquisition Time, Five Times Faster Than Conventional GNSS Receiver
H. So, *Seoul National University, South Korea* ----- 1501

Assessment of Step Determination in a GPS/Compass/IMU System for Personal Positioning
E. Pulido-Herrera, *Universitat Jaume I, Spain*; H. Kaufmann, *Vienna University of Technology, Austria*;
R. Quiros, *Universitat Jaume I, Spain* ----- 1508

Session F3: Galileo Signal Structure, GPS/Galileo Interoperability

The MBOC Modulation: The Final Touch to the Galileo Frequency and Signal Plan
J.A. Avila-Rodriguez, G.W. Hein, S. Wallner, J-L. Issler, L. Ries, L. Lestarquit, A. de Latour,
J. Godet, F. Bastide, T. Pratt, J. Owen, *Members of the Galileo Signal Task Force of the
European Commission* ----- 1515

On Potential CBOC/TMBOC Common Receiver Architectures
O. Julien, C. Macabiau, *ENAC, France*; J.A. Avila-Rodriguez, S. Wallner, M. Paonni,
G.W. Hein, *University FAF Munich, Germany*; J-L. Issler, L. Ries, *CNES, France* ----- 1530

Jitter Analysis of QPSK and BOC(n,n) GNSS Signals
B. Amin, *University of New South Wales, Australia* ----- 1543

**Galileo E1 OS and GPS L1C Pseudo Random Noise Codes Requirements,
Generation, Optimization and Comparison**
S. Wallner, J.A. Avila-Rodriguez, G.W. Hein, *University FAF Munich, Germany*;
J.J. Rushanan, *The MITRE Corporation, USA* ----- 1549

Formal Verification Testing of Galileo RF Constellation Simulators
P. Boulton, A. Read, R. Wong, *Spirent Communications plc, UK* ----- 1564

**First Outdoor Positioning Results with Real Galileo Signals by Using the German Galileo
Test and Development Environment - GATE**
G. Heinrichs, E. Loehnert, E. Wittmann, R. Kaniuth, *IFEN GmbH, Germany* ----- 1576

**Performance Analysis of GIOVE-A Signals in Comparison with GPS Based on Wideband
Measurements with the BayNavTech™ Signal Evaluation Facility (BaySEF™)**
M. Kaindl, M. Soellner, C. Zecha, R. Kohl, *EADS Astrium, Germany* ----- 1588

**Multipath and Tracking Performance of Galileo Ranging Signals Transmitted
by GIOVE-A**
A. Simsky, D. Mertens, J-M. Sleewaegen, T. Willems, *Septentrio Satellite Navigation,
Belgium*; M. Hollreiser, M. Crisci, *ESA/ESTEC, Netherlands*----- 1596

Simulating GNSS Constellations - The GAMMA Signal Generator
C. Abart, P. Berglez, G. Abwerzger, B. Hofmann-Wellenhof, *TeleConsult Austria GmbH, Austria*;
W. Cresens, T. Vandeplass, W. De Win, *AGILENT Technologies, Belgium* ----- 1610

Session A4: Remote Sensing with GPS and Integrated Sensors

**Developing a Low-cost MEMS IMU/ DGPS Integrated System for Robust Machine
Automation**
Y. Geng, A. Cole, A. Dempster, C. Rizos, J. Wang, *University of New South Wales, Australia* ----- 1618

A Kinematic Terrestrial LIDAR Scanning System
C. Glennie, *Terrapoint* ----- 1625

GPS/IMU Error Analysis for Airborne SAR Remote Sensing
L.J. Harcke, R.M. Ueberschaer, J.W. Sinko, J.M. Strus, *SRI International* ----- 1631

An Introduction to Parallel Re-Configurable Receiver Architectures for GNSS Reflections
M. Junered, *Luleå University of Technology, Sweden* ----- 1636

Remote Sensing Stream Flow Discharge & Soil Classification by Using Reflected GPS Observations, L1 & L2 Reflectivity and Digital Terrain Model
L-C. Shen, Y-H. Chen, C-H. Cheng, *National Cheng Kung University, Taiwan*;
C-L. Tseng, *Chia-nan University of Pharmacy & Science, Taiwan*; J-C. Juang,
C-L. Tsai, *National Cheng Kung University, Taiwan* ----- 1643

A Technique for Determining the Carrier Phase Differences Between Independent GPS Receivers During Scintillation
S. Mohiuddin, T.E. Humphreys, M.L. Psiaki, *Cornell University*----- 1651

An Integrated Locata & Leica Geosystems Positioning System for Open-cut Mining Applications
J. Barnes, J. Lamance, *Locata Corporation Pty Ltd., Australia*; B. Lilly, I. Rogers, M. Nix,
Leica Geosystems Pty Ltd., Australia; A. Balls, *DeBeers, South Africa* ----- 1661

Experiments of Low-cost INS/GPS Navigation Platform Based on PC104
N. Hachelef, P. Lavoie, D. Li, R. Landry, *Ecole de Technologie Supérieure, Canada*----- 1669

Session B4: Multipath

High Resolution Multipath Mitigation Technique Based on the Teager-Kaiser Operator for GNSS Signals
D. de Castro, J. Diez, A. Fernández, *Deimos Space S.L., Spain* ----- 1677

Nonlinear Least-Squares Algorithm for Close-in Multipath Mitigation in GNSS Receivers
F.D. Nunes, *Instituto de Telecomunicações and IST, Portugal*; F.M.G. Sousa,
Instituto de Telecomunicações ISEL, Portugal; J.M.N. Leitão, *Instituto de Telecomunicações and IST, Portugal* ----- 1683

A Jump Markov System for Modelling a Realistic Error Model Depending on Satellite Reception State in Urban Environment
D.F. Nahimana, J. Marais, *INRETS/LEOST, France*; E. Duflos, *EC-Lille/LAGIS, France* ----- 1692

A Model for the Suburban Multipath Channel
A. Steingass, A. Lehner, *German Aerospace Center (DLR), Germany* ----- 1699

Structural Deformation/Vibration Monitoring: A Multipath Mitigation Algorithm Based on Wavelet Denoise
D. Lu, *Peking University, China*; M. Cao, *Central South University, China* ----- 1706

Dynamic Multipath Estimation by Sequential Monte Carlo Methods
M. Lentmaier, B. Krach, P. Robertson, *German Aerospace Center (DLR), Germany*;
T. Thiasiriphet, *University of Ulm, Germany* ----- 1712

Parametric and Statistical Characterization of Multipath Errors for Galileo Signals
J.M. López-Almansa, J. Cosmen-Schortmann, P. Coutinho, M. Toledo, *GMV, Spain* ----- 1722

Enhanced Cellular Network Positioning using Space-Time Diversity
A.R.A. Moghaddam, A. Broumandan, G. Lachapelle, J. Nielsen,
University of Calgary, Canada ----- 1733

Novel Algorithm to Exclude Multipath Satellites by Dual Frequency Measurements in RTK-GPS
T. Kashiwayanagi, T. Sekizawa, T. Yamada, K. Yui, M. Nakamura,
Japan Radio Co., Ltd., Japan ----- 1741

Session C4: Novel Applications

Continued Design and Development of the Ohio University Robotic Lawnmower:
D. Bates, F. van Graas, A. Vadlamani, *Ohio University* ----- 1748

Applied Robotics: Multi Purpose Autonomous Vehicle
D. Dube, J. Godin-Viau, L. Bardou-Marchand, *École de Technologie Supérieure, Canada* ----- 1754

Design and Implementation of a Robotic Lawnmower
N.A. Baine, K.S. Rattan, J. Gallagher, S. Thomas, *Wright State University* ----- 1760

Position and Orientation Determination for a Guided K-9
J. Miller, D.M. Bevly, *Auburn University* ----- 1768

A Preliminary Investigation in GNSS Radio Occultation and its Applications in Australian Meteorology
E. Fu, K. Zhang, F. Wu, *RMIT University, Australia* ----- 1777

Achieving the Centimeter Level of Accuracy in Urban Canyons Using LocataLites
J-P. Montillet, *University of Nottingham, UK* ----- 1782

Application of High-Sensitivity GPS for a Highly-Integrated Automated Longitudinal Travel Behavior Diary
K.S. Yen, T.A. Lasky, *University of California-Davis*; A. Adamu, *California Department of Transportation*; B. Ravani, *University of California – Davis* ----- 1790

A Real-Time Position, Velocity, and Physiological Monitoring and Tracking Device for Equestrian Training
K. Green, A. Hill, J. Morton, M. Miller, J. Campbell, *Miami University* ----- 1802

GAPS: The GPS Analysis and Positioning Software – A Brief Overview
R.F. Leandro, *University of New Brunswick, Canada/Trimble Terrasat GmbH, Germany*;
M.C. Santos, R.B. Langley, *University of New Brunswick, Canada* ----- 1807

Autonomous Navigation Environment with Self-Calibrating Transceivers
S. Schlötzer, S. Martin, M.v. Voithenberg, *EADS Astrium GmbH, Germany* ----- 1812

Requirements of an OFDMA Pseudolite Indoor Geolocation System

I.F. Progri, *Giffet Inc.*; M.C. Bromberg, *Elected Engineering*; W.R. Michalson, *Worcester Polytechnic Institute*; J. Wang, *University of New South Wales, Australia*; R.J. Duckworth, *Worcester Polytechnic Institute*; J. Lavrakas, *Advanced Research Corporation* -- 1821

Session D4: Indoor Positioning 2

Performance of Assisted Acquisition of the L2CL Code in a Multi-frequency Software Receiver

A.S. Ayaz, T. Pany, B. Eissfeller, *University FAF Munich, Germany* ----- 1830

Opportunistic Indoor Localization and Navigation Using Wireless LAN (802.11a/g) Signals

H. Xu, L. Yang, *University of Florida* ----- 1839

Adaptive Step Length Estimation with Awareness of Sensor Equipped Location for PNS

C.G. Park, S.H. Shin, *Seoul National University, South Korea*; H.S. Hong, *Samsung Electronics Co. Ltd., South Korea*; J.G. Park, *Kyungpook National University, South Korea* ----- 1845

Tightly-Coupled Image-Aided Inertial Navigation Using the Unscented Kalman Filter

C. Ebcin, M. Veth, *Air Force Institute of Technology* ----- 1851

Positioning and Navigation with Ultra-Wideband Signals

H. Xu, L. Yang, *University of Florida*; Y.T.J. Morton, *Miami University* ----- 1861

Reconstruction of the Satellite Ephemeris From Time-spaced Snippets

P.J. Duffett-Smith, *Cambridge Silicon Radio, UK*; A.R. Pratt, *Orbstar Consultants, UK* ----- 1867

Fully-autonomous Fine Time Aiding to a GPS Receiver in a Cellular Telephone

R. Rowe, M.R. Jarvis, S.D. Hern, P.J. Duffett-Smith, *Cambridge Silicon Radio, UK*; A.R. Pratt, *Orbstar Consultants, UK* ----- 1876

Autonomous GNSS Data Extraction in High Signal Attenuation Conditions

A.R. Pratt, C.R. Offer, *QinetiQ Ltd., UK* ----- 1884

Location Based Services - Ready for Take Off?

G. Abwerzger, E. Wasle, B Hofmann-Wellenhof, *TeleConsult Austria GmbH, Austria* ; J. Hanley, *LogicaCMG, UK Ltd., UK*; J.A. Jimenez Holgado, *Telefonica1+D, Spain*; L. Claverotte, M. Dalmas, *Thales Alenia Space, France*; J. Guard, *Mapflow, Ireland*; M. Fridh, *LogicaCMG, Sweden*; P. Gomes, *Skysoft, Portugal*; O. Lem, *LogicaCMG, The Netherlands*; W. Roberts, *Nottingham Scientific Ltd., UK*; S. Scarda, *European GNSS Supervisory Authority, Belgium* ----- 1894

Session E4: Marine Applications

Performance Evaluation of DGPS versus SBAS/WADGPS for Marine Users

S. Skone, *University of Calgary, Canada*; A. Coster, *MIT Haystack Observatory* ----- 1904

Options for the Modernization of Maritime DGNSS

M. Pattinson, M. Dumville, *Nottingham Scientific Limited, UK*; N. Ward, *General Lighthouse Authorities, UK* ----- 1914

MARUSE Demonstrating the use of Maritime Galileo Pseudolites

A. Grant, N. Ward, *The General Lighthouse Authorities, UK and Ireland*, S.E. Christiansen, *Kongsberg Seatex AS, Norway*; C. Dixon, *EADS Astrium UK*; A. Suskind, *Septentrio Satellite Navigation, Belgium* ----- 1923

A Critical Look at the IMO Requirements for GNSS

J.O. Klepsvik, *Kongsberg Seatex, Norway*; P.B. Ober, *Integricom, The Netherlands*;
M. Baldauf, *Hochschule Wismar, Germany* ----- 1931

VORF - The UK Vertical Offshore Reference Frame: Enabling Real-time GPS Hydrographic Surveying

M. Ziebart, J. Illiffe, J. Turner, J. Oliveira, *University College London, UK*;
R. Adams, *United Kingdom Hydrographic Office, UK* ----- 1943

Experimental Validation of GPS-Based Control of an Unmanned Wing-Sailed Catamaran

G.H. Elkaim, *University of California, Santa Cruz*; C.O. Lee Boyce, *Stanford University* ----- 1950

An Investigation of the Flexible and Rigid Body Response of a Ship Using a GNSS Receiver Network

F.M. Bélanger, A.R.L. Tatnall, *University of Southampton, U.K.* ----- 1957

GNSS/INS Integration: Potential Impact on Maritime Navigation

T. Moore, C. Hill, A. Norris, *University of Nottingham, UK*; C. Hide, D. Park, *Geospatial Research, New Zealand*; N. Ward, *General Lighthouse Authorities, UK* ----- 1964

Session F4: Timing and Scientific Applications

Behavior of the GPS Timing Receivers in the Presence of Interference

F.A. Khan, *University of New South Wales, Australia* ----- 1977

High Accuracy and High Availability Timing System by Using SBAS as Ranging Satellites

M. Tanaka, G. Shinohara, T. Ikeda, *Furuno Electric Co., Ltd., Japan*----- 1983

Real-time Clock and Orbit Corrections for Improved Point Positioning via NTRIP

G. Weber, *Federal Agency for Cartography and Geodesy (BKG), Germany*; L. Mervart, Z. Lukes, C. Rocken, *GPS-Solutions Inc.*; J. Dousa, *Geodetic Observatory Pecny (GOP), Czech Republic* ----- 1992

Scientific Utility of the Signal-to-Noise Ratio (SNR) Reported by Geodetic GPS Receivers

A. Bilich, *National Geodetic Survey*; P. Axelrad, K.M. Larson, *University of Colorado* ----- 1999

GORS - A GNSS Occultation, Reflectometry and Scatterometry Space Receiver

A. Helm, *GeoForschungsZentrum Potsdam, Germany*; O. Montenbruck, *German Aerospace Center, Germany*; J. Ashjaee, S. Yudanov, *JAVAD GNSS, Russia*; G. Beyerle, R. Stosius, M. Rothacher, *GeoForschungsZentrum Potsdam, Germany* ----- 2011

Real-time Synchronisation of a Network of Sensor Stations with High Accuracy and Integrity

C. Hernández, C. Catalán, A.M. Curiel, E. Sardón, *GMV Aerospace & Defence S.A., Spain* ----- 2022

Cracking the GPS - SLR Orbit Anomaly

M. Ziebart, A. Sibthorpe, P. Cross, *University College London, UK*; Y. Bar-Sever, B. Haines, *NASA Jet Propulsion Laboratory* ----- 2033

Beginning of Precise Time Transfer Experiment Using ETS-VIII Satellite

Y. Takahashi, F. Nakagawa, T. Gotoh, J. Amagai, S. Hama, *National Institute of Information and Communications Technology (NICT), Japan*; H. Noda, *Japan Aerospace Exploration Agency (JAXA), Japan* ----- 2039

Session A5: GNSS/INS 1

Inertial Navigation Versus Pedestrian Dead Reckoning: Optimizing the Integration

P.D. Groves, G.W. Pulford, C.A. Littlefield, D.L.J. Nash, C.J. Mather, *QinetiQ Ltd., UK* ----- 2043

In Flight Estimation of Gyro and Accelerometer Scale Factors for Tactical and MEMS IMUs

M. Becker, U. Bestmann, A. Sasse, M. Steen, P. Hecker, *Technical University of Braunschweig, Germany* ----- 2056

Low-cost PND Dead Reckoning using Automotive Diagnostic Links

J.L. Wilson, *STMicroelectronics, Inc.* ----- 2066

Assessment of the Integration Strategy Between GPS and Body-Worn MEMS Sensors with Application to Sports

A. Waegli, J. Skaloud, P. Tomé, J-M. Bonnaz, *École polytechnique Fédérale de Lausanne, Switzerland* ----- 2075

Integration of MEMS INS with GPS Carrier Phase Derived Velocity: A New Approach

W. Ding, *The University of New South Wales, Australia* ----- 2085

Real-time Processing and Flight Demonstration of a Low Cost MEMS-based GPS/INS, Micro-GAIA

H. Tomita, T. Fujiwara, T. Tsujii, M. Harigae, *Japan Aerospace Exploration Agency, Japan* ----- 2094

Attitude Determination Using a Multi-antenna GNSS Receiver Tightly Integrated with a MEMS IMU

J.F.M. Lorga, P.F. Silva, J.S. Silva, *DEIMOS Engenharia S.A., Portugal*; A. Fernández, *DEIMOS Space S.L., Spain* ----- 2102

AsteRx High-End GNSS Receiver Coupled with MEMS-based IMU for Industrial Applications

L. Vander Kuylen, J. Gao, F. Boon, *Septentrio Satellite Navigation, Belgium* ----- 2113

Intelligent Tuning of a Kalman Filter for INS/GPS Navigation Applications

C. Goodall, *The University of Calgary, Canada*; X. Niu, *SiRF Technology Inc.*; N. El-Sheimy, *The University of Calgary, Canada* ----- 2121

Economical and Robust Inertial Sensor Configuration for a Portable Navigation System

Z. Syed, P. Aggarwal, X. Niu, N. El-Sheimy, *The University of Calgary, Canada* ----- 2129

Session B5: Surveying and Geodesy

The International GNSS Service (IGS): Preparations for the Coming Decade

J.M. Dow, *ESA/ESOC, Germany*; R.E. Neilan, *Jet Propulsion Laboratory*; C. Rizos, *University of New South Wales, Australia* ----- 2136

The North America Reference Frame (NAREF) Project to Densify the ITRF in North America

M.R. Craymer, M. Piraszewski, J.A. Henton, *Natural Resources Canada, Canada* ----- 2145

NAVD88 Orthometric Height Determination Utilizing the California Real Time GPS Network

C. Whitaker, *Metropolitan Water District of Southern California*; G.A. Helmer, *RBF Consulting, Inc.*; Y. Bock, *Scripps Institution of Oceanography*; K.J. Launen, D.E. Morgan, *Psomas & Associates, Inc.* ----- 2155

GNSS Applications in Airborne and Seaborne Sea Surface Height Measurements

P. Limpach, A. Geiger, H-G. Kahle, *Geodesy and Geodynamics Lab, Switzerland* ----- 2163

A New Framework for Server-Based and Thin-Client GNSS Operations for High Accuracy Applications in Surveying and Navigation

S. Lim, C. Rizos, *University of New South Wales, Australia* ----- 2169

Filtering Techniques to Detect Millimetric-scale Dynamic Displacements

R.E. Schaal, A.P.C. Larocca, *University of Sao Paulo, Brazil* ----- 2178

GPS Signal Disturbances by Water in Various States

C. Gernot, *The University of Calgary, Canada* ----- 2187

L1 RTK System with Fixed Ambiguity: What SBAS Ranging Brings

A. Boriskin, D. Kozlov, G. Ziryanov, *Magellan, Russia* ----- 2196

Satellite Augmentation Systems for Acceleration Determination in Airborne Gravimetry: A Comparative Study

M. Sahmoudi, R. Landry, I. Ilie, T. Delaporte, *Ecole de Technologie Superieure, Canada* ----- 2202

Characteristics of Carrier Phase Measurements of an Inner Antenna in a Vehicle for RTK-GPS

T. Sekizawa, T. Kashiwayanagi, T. Yamada, K. Yui, M. Nakamura, *Japan Radio Co., Ltd., Japan* ----- 2210

Session C5: Software Receivers 1

Portable GPS Baseband Logging

M. Quigley, P. Abbeel, D. De Lorenzo, Y. Gu, S. Bolouki, *Stanford University*; D. Akos, *University of Colorado*; A.Y. Ng, *Stanford University* ----- 2216

An Open Source GNSS Reference Server

T. Yan, P. Mumford, A. Dempster, C. Rizos, *University of New South Wales, Australia*; M. Fernando, N. Hoang, *University of Technology, Australia* ----- 2224

Improvements to "A Software-Defined GPS and Galileo Receiver: Single-Frequency Approach"
E. Vinande, D. Akos, *University of Colorado at Boulder* ----- 2230

Implementation, Verification and Test Results of a MLE-based F-Correlator Method for Multi-Frequency GNSS Signal Trackings
J-H. Won, T. Pany, B. Eissfeller, *University FAF Munich, Germany*----- 2237

A DSP/FPGA Design for the Acquisition and Tracking of GIOVE-A Signals
T-L. Kao, Y-H. Chen, J-C. Juang, *National Cheng Kung University, Taiwan*----- 2250

Development of a One Channel Galileo L1 Software Receiver and Testing Using Real Data
F. Macchi, M.G. Petovello, *The University of Calgary, Canada*----- 2256

An Integrated Software Defined Radio Navigation System for Space Navigation
B. Mathews, A. Brown, *NAVSYS Corporation*----- 2270

Host-Based GPS an Emerging Architecture for High Volume Consumer Applications
C. Abraham, F. van Diggelen, *Broadcom Corporation* ----- 2279

Session D5: Atmospheric Effects on GNSS 1

Generating a 3D TEC Model for Australia with Combined LEO Satellite and Ground Based GPS Data
G. Ouyang, Jian Wang, Jinling Wang, *University of New South Wales, Australia*; D. Cole, *IPS Radio and Space Services, Australia* ----- 2285

Combining L1 L2 Carriers Differences with Ionosphere Model Estimates for an Improved Ionosphere Error Corrector
D. Dodd, *University of Southern Mississippi*; S. Bisnath, *York University, Canada* ----- 2291

Positioning Impacts from Imbalanced Atmospheric GPS Network Errors
Y.W. Ahn, D. Kim, P. Dare, *University of New Brunswick, Canada* ----- 2302

Ionospheric Measurement with GPS: Receiver Techniques and Methods
L. Dyrud, A. Jovancevic, S. Ganguly, *Center for Remote Sensing, Inc.* ----- 2313

Ionospheric Analysis in the Equatorial Region: Impact on GNSS Performances
M. Cueto, A. Cezón, S. Pineda, E. Sardón, *GMV, Spain* ----- 2324

Imaging the Ionospheric Electron Density Using a Combined Tomographic Algorithm
D. Wen, *Chinese Academy of Sciences, China* ----- 2337

Ionospheric Estimation Over Japan Based on GNSS Regression Models and GEONET Data
S. Sugimoto, Y. Kubo, S. Fujita, T. Imamura, T. Kazuno, *Ritsumeikan University, Japan* ----- 2346

Session E5: Space and Satellite Applications

Constrained Beamforming for Space GPS Navigation

A. Brown, B. Mathews, *NAVSYS Corporation* ----- 2357

High Dynamics and False Lock Resistant GNSS Carrier Tracking Loops

P.A. Roncagliolo, J.G. Garcia, *Universidad Nacional de La Plata, Argentina* ----- 2364

The GREHDA Project: Galileo Software Receiver for High Dynamic Applications

A. Di Cintio, *Carlo Gavazzi Space SpA, Italy*; O. Montenbruck, *DLR/GSOC, Germany*;
L. Lo Presti, R. Lesca, *Politecnico di Torino, Italy*; E. Guyader,
European GNSS Supervisory Authority ----- 2376

A Strategy for Geostationary Positioning with GNSS Signals

B. Chibout, C. Macabiau, A.C. Escher, *ENAC/TeSA, France*; L. Ries, J.L. Issler, *CNES, France*; S. Corazza, *Thales Alenia Space* ----- 2388

Use of Two-Way Time Transfer Measurements to Improve Geostationary Satellite Navigation

B. Dainty, J.F. Raquet, R. Beckman, *Air Force Institute of Technology* ----- 2401

In-Orbit Results From a Space-borne GPS Attitude Experiment

S.M. Duncan, M.S. Hodgart, *University of Surrey, UK*; M.J. Unwin, R. Hebden,
Surrey Satellite Technology Limited ----- 2412

GPS-Based Attitude Determination for Microsatellites

A. Hauschild, O. Montenbruck, *DLR, German Space Operations Center, Germany* ----- 2424

A Spaceborne Formation Flying RF System in S-band Reusing the GPS Standards

L. Lestarquit, T. Grelier, J. Harr, E. Peragin, J-L. Issler, *CNES, France*;
N. Wilhelm, C. Mehlen, *Thales Alenia Space, France*; A. Garcia, J.L. Gerner,
ESTEC, Netherlands ----- 2435

Use of Rubidium GPS Receiver Clocks to Enhance Accuracy of Absolute and Relative Navigation and Time Transfer for LEO Space Vehicles

D.B. Cox, Jr., *DBC Communications, Inc.*; J.D.W. Brading, *Consultant* ----- 2442

Reconfigurable GPS-Galileo Receiver for Satellite Based Applications

A. Dion, V. Calmettes, *SUPAERO/TeSA, France*; E. Boutillon, *LESTER, France* ----- 2448

Galileo Primary Code Acquisition Based on Multi-hypothesis Secondary Code Ambiguity Elimination

G.E. Corazza, C. Palestini, R. Pedone, M. Villanti, *DEIS/ARCES, University of Bologna, Italy* ----- 2459

Session F5: GPS Modernization/GPS III

Working Without a Net - Operating the Modernized GPS Block IIR Space Vehicles Prior to OCX

W. Marquis, *Lockheed Martin Space Systems* ----- 2466

Validation of the New GPS Master Control Station Using GPS User Equipment
A. Fisher, *USAF 746 Test Squadron*; J. Doucet, *USAFR, 19th Space Operations Squadron* ----- 2478

Summary of Accuracy Improvements from the GPS Legacy Accuracy Improvement Initiative (L-All)
T. Creel, *National Geospatial-Intelligence Agency*; A.J. Dorsey, *Lockheed-Martin Corporation*;
P.J. Mendicki, *The Aerospace Corporation*; J. Little, R.G. Mach, B.A. Renfro,
The University of Texas at Austin ----- 2481

Evaluation of Data/Pilot Tracking Algorithms for GPS L2C Signals Using Software Receiver
K. Muthuraman, S.K. Shanmugam, G. Lachapelle, *University of Calgary, Canada* ----- 2499

Evaluation of L2C Observations and Limitations
O. al-Fanek, S. Skone, G. Lachapelle, *University of Calgary, Canada*; P. Fenton,
NovAtel Inc., Canada ----- 2510

Data Message Performance for the Future L1C GPS Signal
P.A. Dafesh, E.L. Vallés, J. Hsu, D.J. Sklar, L.F. Zapanta, *The Aerospace Corporation*;
C.R. Cahn, *Consultant to The Aerospace Corporation* ----- 2519

The Precise Positioning Service (PPS) Performance Standard (PS)
K. Kovach, *Aerospace Corporation*; J. Taylor, *U.S. Air Force*; A. Elliott, *A.E. Engineering & Consulting*; D. Steare, *Jacobs Technology, Inc.* ----- 2529

Session A6: GNSS/INS 2

Development of a High Accuracy Pointing System for Maneuvering Platforms
J.M. Strus, M. Kirkpatrick, J.W. Sinko, *SRI International* ----- 2541

The Open Loop Design for an ANN-RTS Smoother Hybrid Scheme for Accurate INS/GPS Integrated Attitude Determination
Y-C. Lin, *National Cheng Kung University, Taiwan* ----- 2550

Ultra Tightly Coupled GPS/INS Receiver for TSPI Applications
L. Dyrud, B. Woessner, A. Jovancevic, S. Ganguly, *Center for Remote Sensing, Inc.* ----- 2563

User Level Integrity Monitoring and Quality Control for Seamless Positioning in all Conditions and Environments
W.Y. Ochieng, S. Feng, *Imperial College London, UK*; T. Moore, C. Hill, *University of Nottingham, UK*; C. Hide, *Geospatial Research Centre, New Zealand* ----- 2573

Discrete vs. Continuous Carrier Tracking Loop Theory, Implementation, and Testing with Large BnT
I.F. Proгри, *Giftet Inc.*; C.W. Kelley, *Open Source GPS*; G. Gao, *University of Calgary, Canada*;
W.R. Michalson, *Worcester Polytechnic Institute*; J. Wang, *University of New South Wales, Australia*; J. Lavrakas, *Advance Research Corporation* ----- 2584

Comparison of State and Error State INS Coupling Filter Based on Real Flight Test Data
U. Bestmann, M. Steen, M. Becker, A. Sasse, P. Hecker, *Technical University of Braunschweig, Germany* ----- 2611

Extended Particle Filter (EPF) for INS/GPS Land Vehicle Navigation Applications
P. Aggarwal, D. Gu, S. Nassar, Z. Syed, N. El-Sheimy, *The University of Calgary, Canada* ----- 2619

Demonstration of Non-coherent Deep INS/GPS Integration for Optimised Signal-to-noise Performance
P.D. Groves, C.J. Mather, A.A. Macaulay, *QinetiQ Ltd., UK* ----- 2627

Modified Gaussian Sum Filtering Methods for INS/GPS Integrated System
Y. Kubo, T. Sato, *Ritsumeikan University, Japan*; M. Nishiyama, *Nippon GPS Solutions Corp., Japan*; S. Sugimoto, *Ritsumeikan University, Japan* ----- 2639

Performance Evaluation of Extended and Unscented Kalman Filter in a High Dynamic Environment on Flight Trials
M. Steen, A. Sasse, U. Bestmann, M. Becker, P. Hecker, *Technical University of Braunschweig, Germany* ----- 2650

Autonomous Fault Detection on a Low Cost GPS-Aided 3-Axis Attitude Determination System
A.C. Louro, R.V.F. Lopes, H.K. Kuga, *Instituto Nacional de Pesquisas Espaciais, Brazil* ----- 2658

Session B6: Modeling and Simulation

A Virtual Navigation System and Solutions of Extraterrestrial Disturbances
G. Xu, *GeoForschungsZentrum Potsdam, Germany*; X. Lu, X. Li, *National Time Service Center* ----- 2668

Factored Correlator Model: A Solution for Fast, Flexible and Realistic GNSS Receiver Simulations
J.S. Silva, P.F. Silva, *DEIMOS Engenharia S.A., Portugal*; A. Fernández, J. Diez, *DEIMOS Space S.L., Spain*; J.F.M. Lorga, *DEIMOS Engenharia S.A., Portugal* ----- 2676

Multipath Signal Simulation in a Dynamic Aircraft Landing Environment
J.P. Weiss, P. Axelrad, *University of Colorado, Boulder* ----- 2687

Prediction of Urban GNSS Availability and Signal Degradation Using Virtual Reality City Models
J. Bradbury, *University College London, UK* ----- 2696

Enhancing Usability of the GRANADA Bit-True Receiver Simulation on Galileo L1
H. Hurskainen, X. Hu, *Tampere University of Technology, Finland*; S. Ancha, G. Bell, *PA Consulting Group, Cambridge Technology Center, UK*; J. Raasakka, J. Nurmi, *Tampere University of Technology, Finland* ----- 2707

The Squaring-Loss Paradox
C. Strässle, D. Megnet, H. Mathis, *University of Applied Sciences Rapperswil, Switzerland*; C. Bürgi, *u-blox AG, Switzerland* ----- 2715

Session C6: Software Receivers 2

ITACA: a Scientific GNSS Software Receiver for Innovation Creation and Testing

A. Tomatis, F. Dovis, *Politecnico di Torino, Italy*; M. Pini, M. Fantino, *Istituto Superiore Mario Boella, Italy* ----- 2723

Creating a GNSS Receiver From Free Software Components

T. Danielsen, *The Norwegian University of Science and Technology, Norway* ----- 2731

An Open Source Software Receiver for Bistatic Remote Sensing

S. Gleason, *QinetiQ Ltd. UK* ----- 2742

Performance Evaluation of a Multi-frequency GPS/Galileo/SBAS Software Receiver

M. Anghileri, T. Pany, D. Sanromà, Güixens J-H. Won, A.S. Ayaz, C. Stöber, I. Krämer, D. Dötterböck, G.W. Hein, B. Eissfeller, *University FAF Munich, Germany* ----- 2749

Wigner-Hough/Randon Transform for GPS Post-Correlation Integration

C. Yang, *Sigtem Technology, Inc.*; M. Miller, *AFRL/MNG*; T. Nguyen, *AFRL/SNRN*; E. Blasch, *AFRL/SNAA* ----- 2762

A GNSS Software Receiver Approach for the Processing of Intermittent Data

Y-H. Chen, J-C. Juang, *National Cheng Kung University, Taiwan* ----- 2772

Evaluating Receiver Architectures for Inertial Aiding and Coasting

P.F. Silva, J.S. Silva, J.F.M. Lorga, *DEIMOS Engenharia S.A., Portugal*; A. Fernandez, J. Diez, *DEIMOS Space S.L., Spain*; M. Wis, M.E. Parés, I. Colomina, *Institute of Geomatics, Spain* ----- 2778

Anti-Jamming Technique Performance Evaluation for GPS L1 C/A Software Receiver

S-H. Im, J-H. Song, B-H. Lee, G-I. Jee, S-Y. Han, *Konkuk Universtiy, South Korea*; J-S. Bae, J-O. Kim, *Agency for Defense Development, South Korea* ----- 2787

Tracking of Weak GPS Signal with BACIX

C. Yang, *Sigtem Technology, Inc.*; S. Han, *SiRF Technology Inc.* ----- 2797

Development of the Open Source GPS Software Receiver Emulator

C.W. Kelley, *Open Source GPS*; F. Niles, *Consultant*; D. Baker, *GPS Creations* ----- 2808

A Novel Scheme and Modified Structure for Improved Software GPS Receiver

C-F. Chang, R-M. Yang, *National Space Organization, Taiwan*; M-S. Kao, *National Chiao-Tung University, Taiwan*; J-C. Juang, *National Cheng-Kung University, Taiwan* ----- 2813

Session D6: Atmospheric Effects on GNSS 2

Investigation of Storm Enhanced Density Effects in Southern Hemisphere

S. Skone, *University of Calgary, Canada*; A. Coster, *MIT Haystack Observatory* ----- 2823

Evaluation of Tracking Performance in the Presence of Ionospheric Scintillation on GPS Signal in Japan

S-I. Kondo, T. Ebinuma, N. Kubo, A. Yasuda, *Tokyo University of Marine Science and Technology, Japan* ----- 2832

Modeling the 20 November 2003 Ionosphere Storm with GRACE	
S. Datta-Barua, T. Walter, S. Pullen, P. Enge, <i>Stanford University</i>	2840
PPP-based Ionospheric Activity Monitoring	
R.F. Leandro, <i>University of New Brunswick, Canada/Trimble Terrasat GmbH, Germany</i> ; M.C. Santos, R.B. Langley, <i>University of New Brunswick, Canada</i>	2849
Evaluation and Comparison of Different Methods of Ionospheric Delay Mitigation for Future Galileo Mass Market Receivers	
A. Somieski, C. Bürgi, E. Favey, <i>u-blox AG, Switzerland</i>	2854
GPS-Tomography for Meteorology: Impact on Operational Weather Forecast	
M. Troller, A. Geiger, D. Perler, H-G. Kahle, <i>Institute of Geodesy and Photogrammetry, Switzerland</i> ; D. Leuenberger, <i>Federal Office of Meteorology and Climatology, Switzerland</i> ; E. Brockmann, <i>Swiss Federal Office of Topography, Switzerland</i>	2861
A Climatic Based Asymmetric Mapping Function Using a Dual Radiosonde Raytracing Approach	
R. Ghoddousi-Fard, P. Dare, <i>University of New Brunswick, Canada</i>	2870
Development of a Regional Ionosphere Model for Norway	
A.B.O. Jensen, <i>AJ Geomatics, Denmark</i> ; O. Ovstedal, <i>Norwegian University of Life Sciences, Norway</i> ; G. Grinde, <i>Norwegian Mapping Authority, Norway</i>	2880
Real-Time Water Vapor Sensing/Measurements with Precise Point Positioning Algorithm and Canadian Geodetic (GPS) Network	
W. Tao, Y. Gao, Y. Zhang, <i>The University of Calgary, Canada</i>	2890
Session E6: Aviation Applications	
Feasibility Analysis of RAIM to Provide LPV-200 Approaches with Future GPS	
Y.C. Lee, M.P. McLaughlin, <i>The MITRE Corporation/CAASD</i>	2898
A GLR Algorithm to Detect and Exclude up to Two Simultaneous Range Failures in a GPS/Galileo/ IRS Case	
A. Giremus, <i>Université de bordeaux, France</i> ; A-C. Escher, <i>ENAC, France</i>	2911
An Optimized Multiple Hypothesis RAIM Algorithm for Vertical Guidance	
J. Blanch, A. Ene, T. Walter, P. Enge, <i>Stanford University</i>	2924
Integrated GNSS/Altimeter Landing System	
R. Braff, <i>The MITRE Corporation/CAASD</i>	2934
Airport Surface Movement - Performance Requirements, Architecture Considerations and Integrity Algorithms	
W. Schuster, J. Bai, S. Feng, W. Ochieng, <i>Imperial College London, UK</i>	2950
The Baseline Constrained LAMBDA Method for Single Epoch, Single Frequency Attitude Determination Applications	
P. Buist, <i>Delft University of Technology, The Netherlands</i>	2962

GPS Antenna Group Delay Variation Induced Errors in a GNSS Based Precision Approach and Landing Systems
T. Murphy, *Boeing Commercial Airplanes*; P. Geren, T. Pankaskie,
Boeing Integrated Defense Systems ----- 2974

Theoretical and Statistical Evaluation of the Physical Height Loss Experienced During Missed Approach by a Heavy Aircraft Under Vertical Instrument Guidance
D.P. Stapleton, *Innovative Solutions International/FAA AFS 420* ----- 2990

An Innovative Approach to Overcome GPS Signal Masking During Maneuvers in Aircraft or Satellite
G. Vyasraj, S.B. Vijay, *Accord Software and Systems Pvt. Ltd., India* ----- 2999

Session F6a: GLONASS Modernization, QZSS, and Other GNSS

Introduction of IS-QZSS (Interface Specification for Quasi Zenith Satellite System)
S. Kogure, M. Kishimoto, M. Sawabe, K. Terada, *Japan Aerospace Exploration Agency, Japan* ----- 3008

Compass Signal Structure and First Measurements
T. Grelier, A. Ghion, J. Dantepal, L. Ries, A. de Latour, J-L. Issler, *CNES, France*;
J.A. Avila-Rodriguez, S. Wallner, G.W. Hein, *University FAF Munich, Germany* ----- 3015

Autonomous Low Cost Regional Navigation Satellite Systems Based on Geosynchronous Eccentric and Inclined Orbits
M.M. Romay Merino, M.D. Lainez Samper, A.J. Gavín Alarcón, A. Guerra Quijada,
GMV, Aerospace and Defence S.A., Spain ----- 3025

Russian System for Differential Correction And Monitoring: A Concept, Present Status, and Prospects for Future
S.V. Averin, V.V. Dvorkin, S.N. Karutin, *Russian Institute of Space Device Engineering (FSUE "RISDE"), Russia* ----- 3037

Session F6b: Galileo Integrity Multi-constellation RAIM

GPS/Galileo RAIM Performance in Presence of Multiple Pseudorange Failures due to Interference
A. Martineau, C. Macabiau, O. Julien, *ENAC, France*; I. Nikiforov, *UTT, France*;
B. Roturier, *DTI, France* ----- 3045

GNSS Multi-System Integrity Algorithm Definition and Evaluation
P. D'Angelo, A. Fernández, *DEIMOS Space S.L., Spain* ----- 3057

How Many Satellites are Necessary to Provide APV Everywhere?
H.L. Trautenberg, *EADS Astrium, Germany* ----- 3064

Integrity Monitoring Algorithms Using Filtering Approaches for Higher Navigation Performance: Consideration of the Non-Gaussian GNSS Measurements
Y. Yun, D. Kim, *Seoul National University, South Korea* ----- 3070